

# Diagnostic of welded structures using laser interferometry methods

L. Lobanov      V. Pivtorak      V. Savitsky\*

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**13th Summer School on Fracture Mechanics  
Trzebnica, 3–6th September 2013**



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E. O. Paton Electric Welding Institute, Kiev



## **Diagnostics of welded structures using laser interferometry methods**



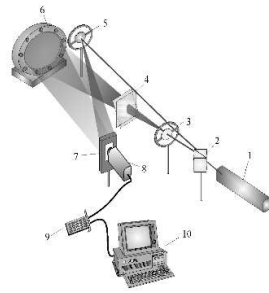
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\*Paton Electric Welding Institute, Kiev

# laser interferometry ]

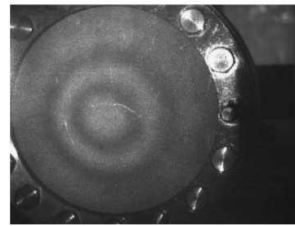
## Holographic interferometry

## Holographic interferometry



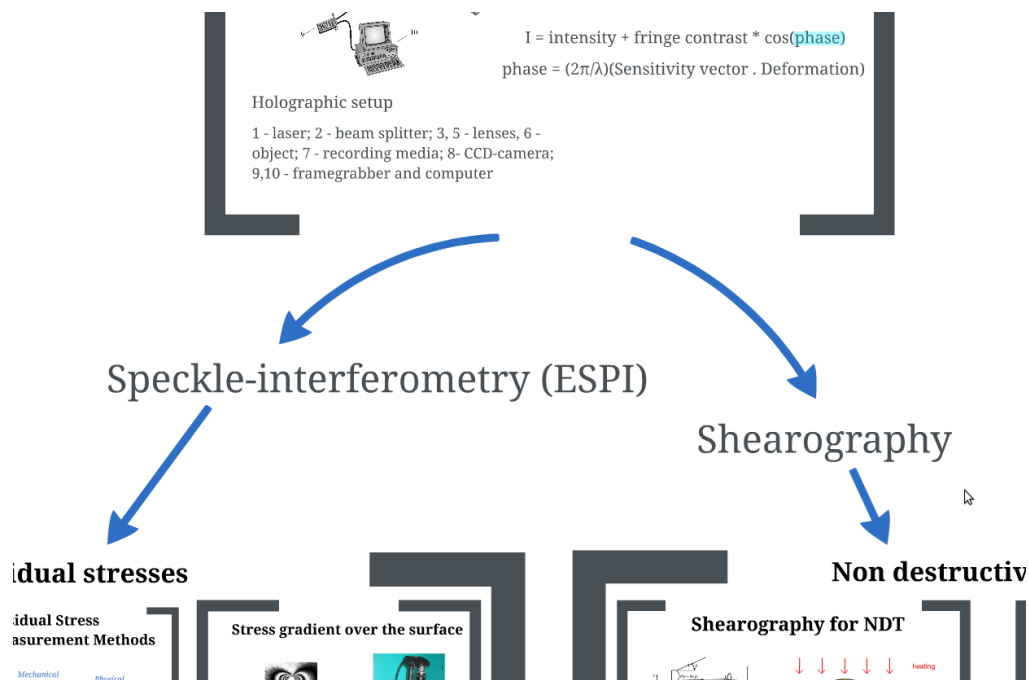
Holographic setup

1 - laser; 2 - beam splitter; 3, 5 - lenses, 6 - object; 7 - recording media; 8- CCD-camera; 9,10 - framegrabber and computer



$$I = \text{intensity} + \text{fringe contrast} * \cos(\text{phase})$$

$$\text{phase} = (2\pi/\lambda)(\text{Sensitivity vector} \cdot \text{Deformation})$$



### Determination of Residual stresses

**Formation of residual stresses**

- Mechanical [1]
- Thermal [2]
- Metallurgical
- Chemical

**Effect of Residual Stresses**

1. Increase of yield strength
2. Increase of fatigue crack growth rate
3. Increase of stress intensity factor
4. Increase of stress intensity factor

**Residual Stress Measurement Methods**

Mechanical      Physical

Strain-gauge      Photoelasticity

Semi-destructive      Destructive

**Stress gradient over the surface**

**Speckle-interferometry**

Principle of operation

Mathematical description

Experimental setup

**Displacement measuring using ESPI-method**

**Residual stresses calculation using displacements data around a hole**

Mathematical model

Experimental setup

**Determination of coefficients A, B or C**

**Determination of residual stresses using speckle-interferometry method**

Equipment for determination of the coefficients

Calibration of the measurement system

Determination of the displacement

**Determination of residual stresses in a railway wheel using ESPI-HD method**

The use of the ESPI method in residual stress determination is based on the principle of optical interference. The method is non-destructive and allows for the measurement of surface displacements with high precision. The resulting data is used to calculate the residual stress distribution in the material.

## What is Residual Stresses?

"the stress resident inside a component or structure after all applied forces have been removed"

Residual stress cannot be detected or evaluated by conventional surface measurement techniques, since the strain sensor (strain gage, photoelastic coating, etc.) can only respond to strain changes that occur after the sensor is installed

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## Formation of residual stresses

Mechanical 

Thermal 

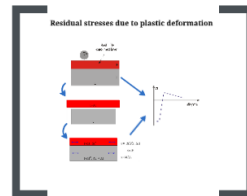
Metallurgical (Phase transformations with volume changes etc.)

Chemical (Carburizing and nitriding are similar to induction hardening, except the surface compressive residual stresses and case depth are not as deep.)

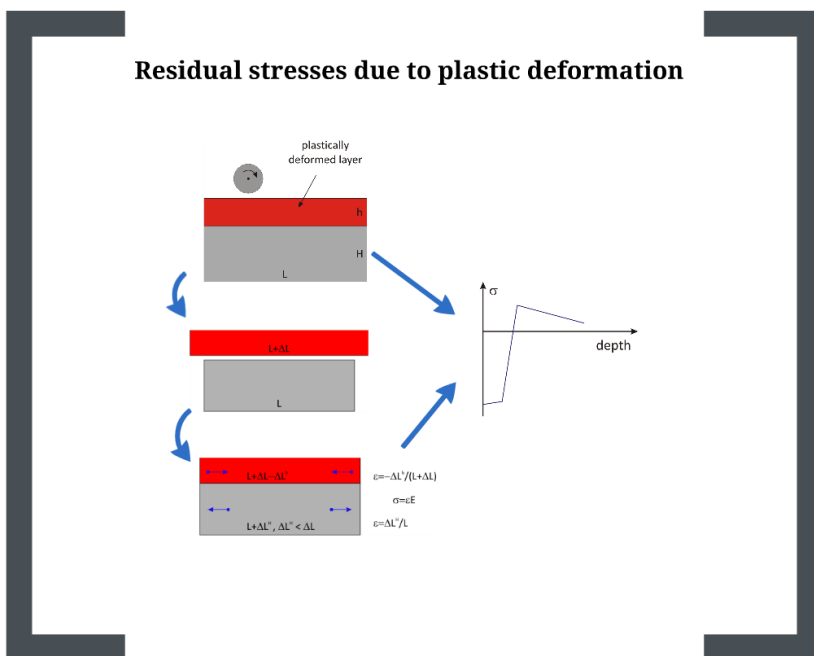
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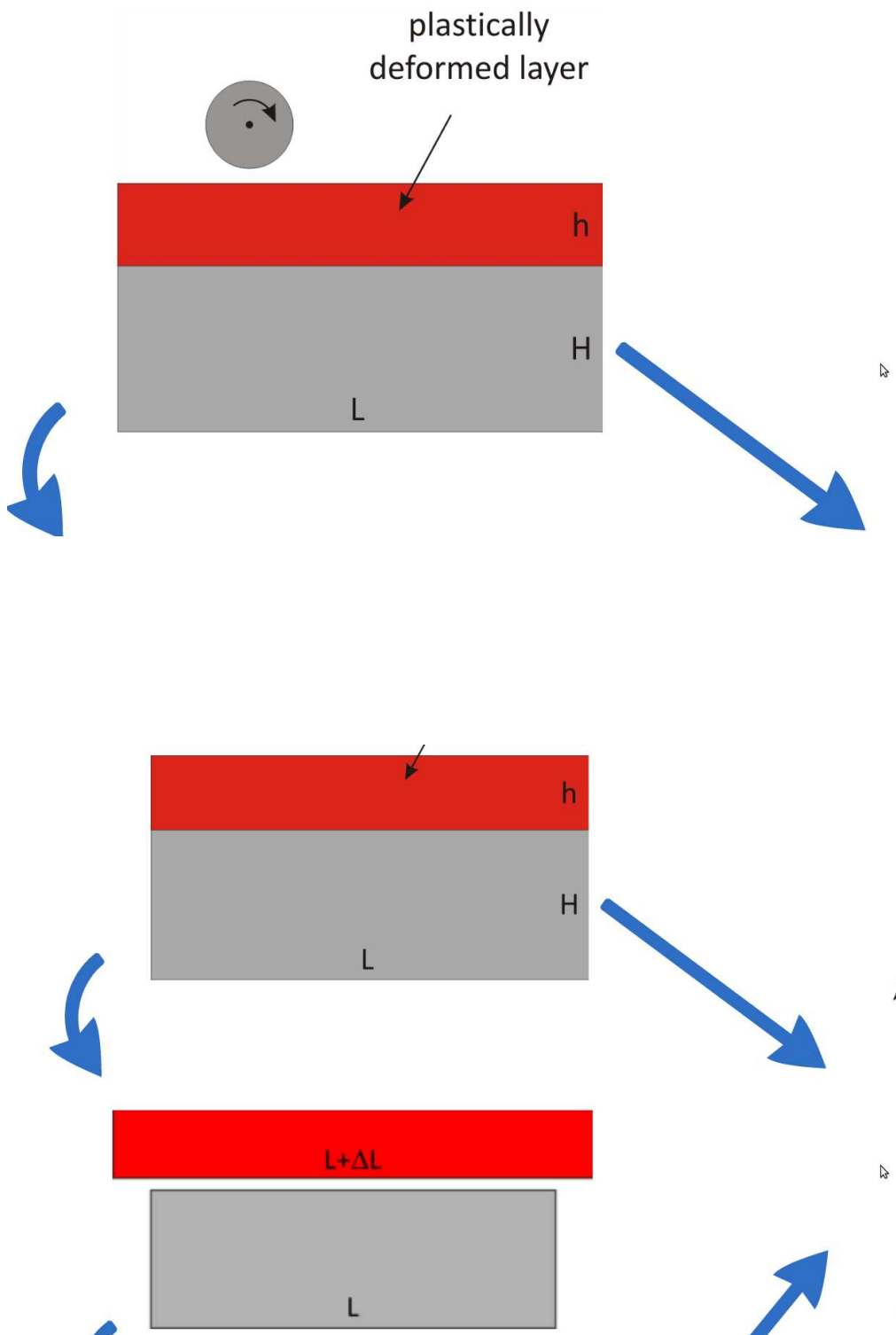
# Mechanical

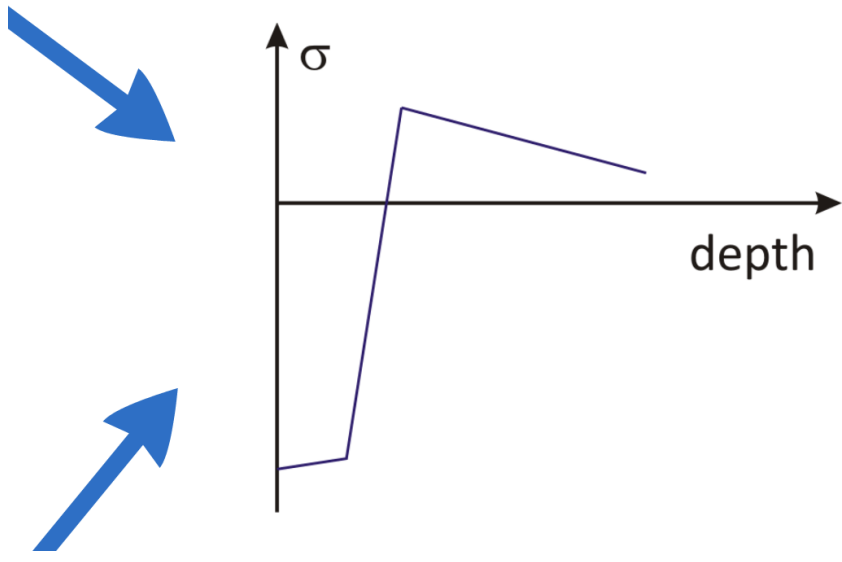
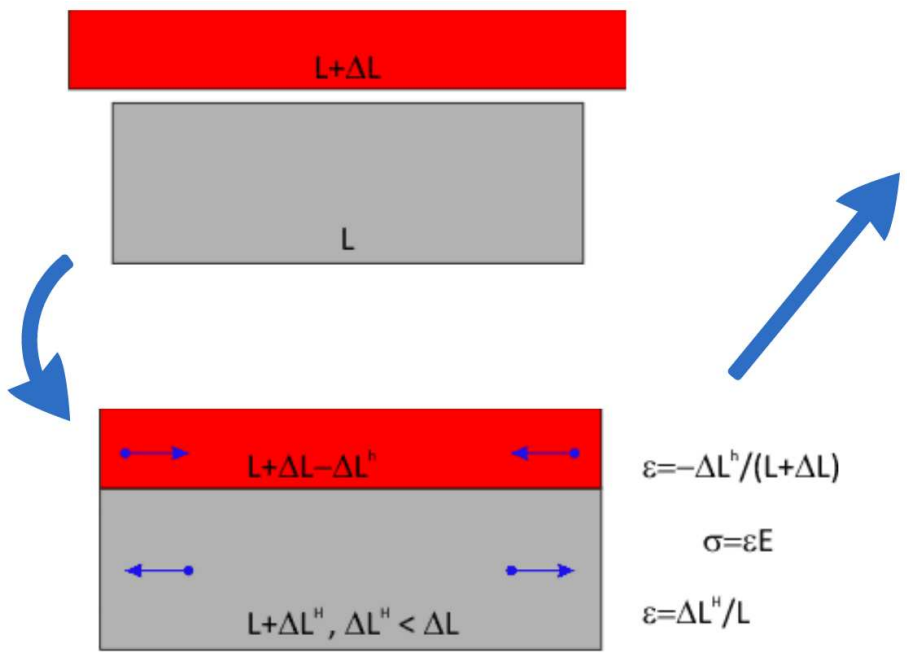


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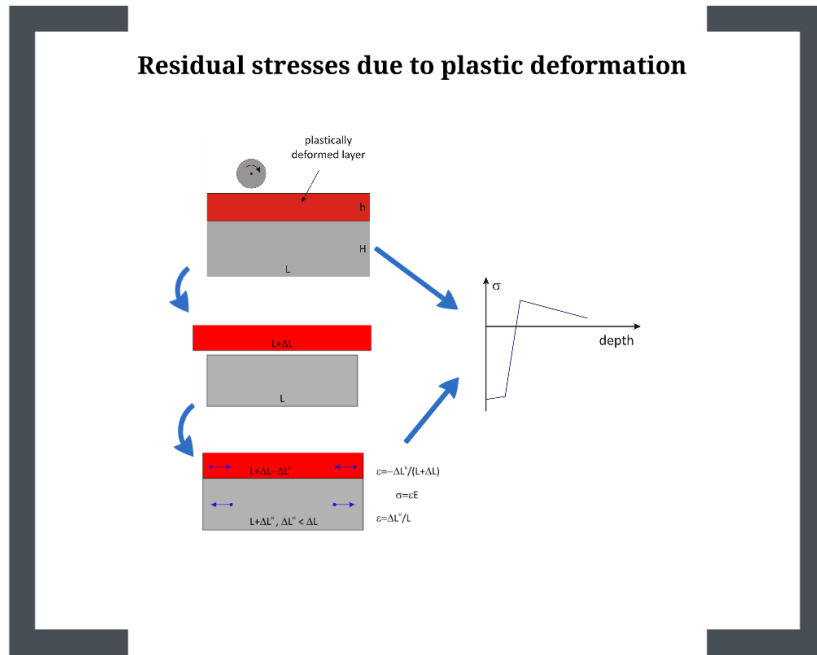
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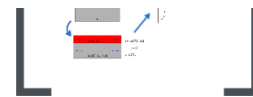


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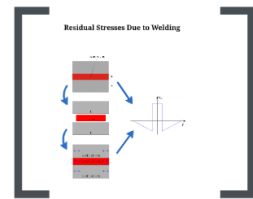
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Mechanical



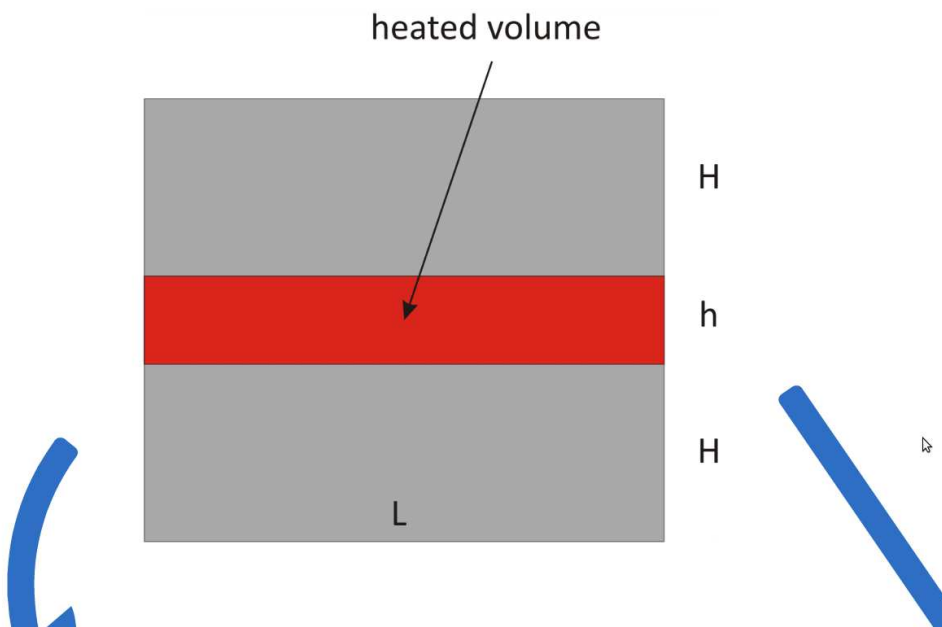
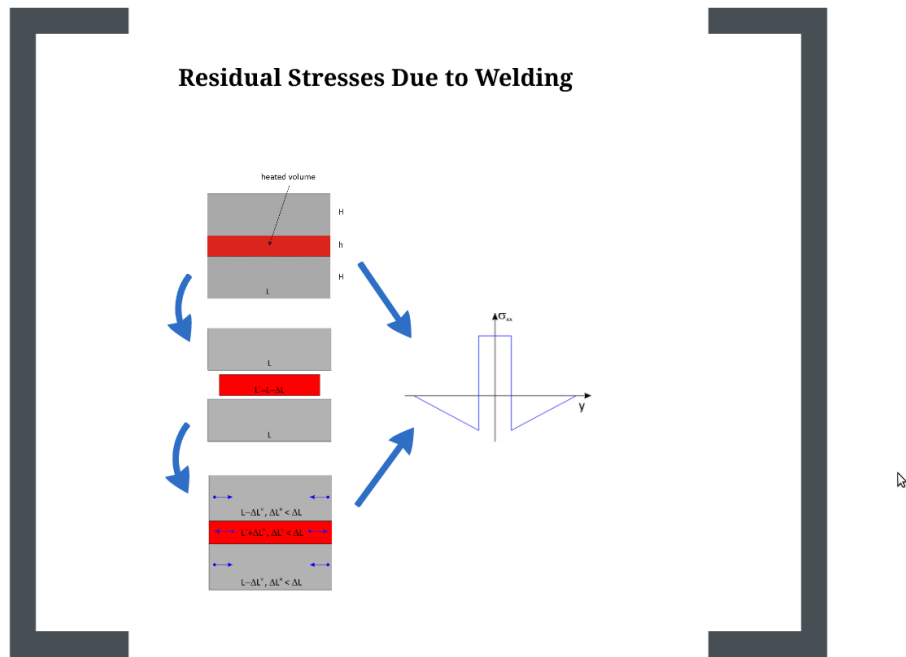
Thermal

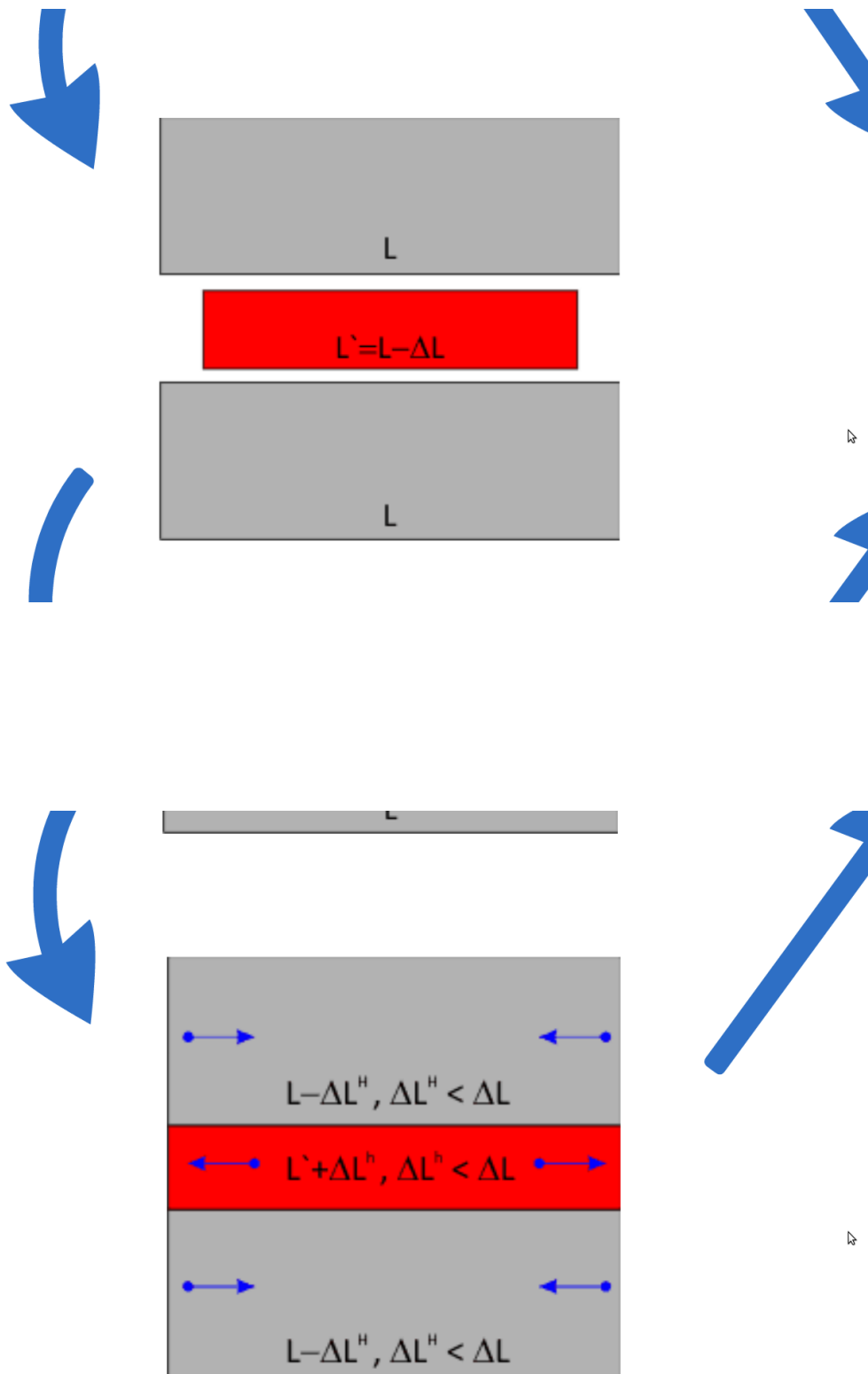


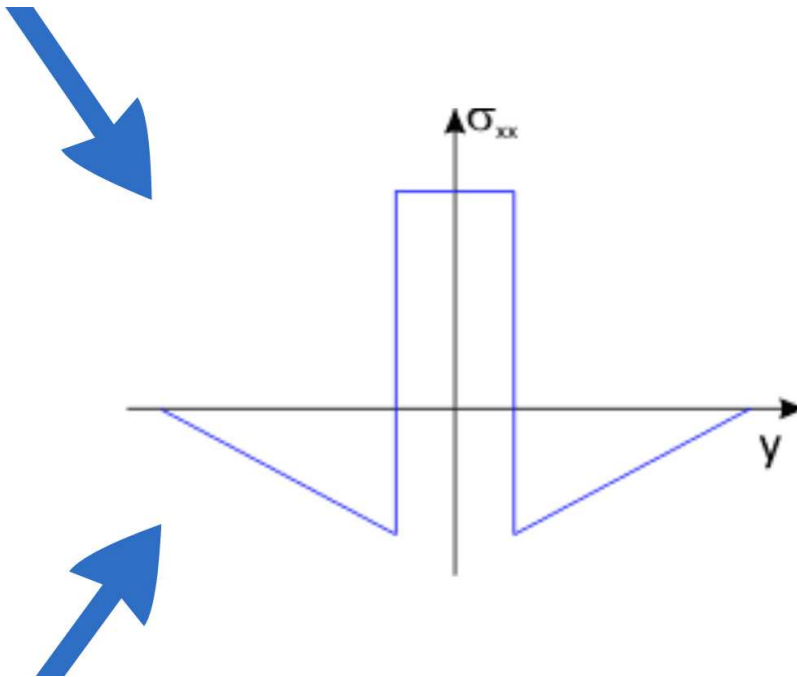
Metallurgical

(a)

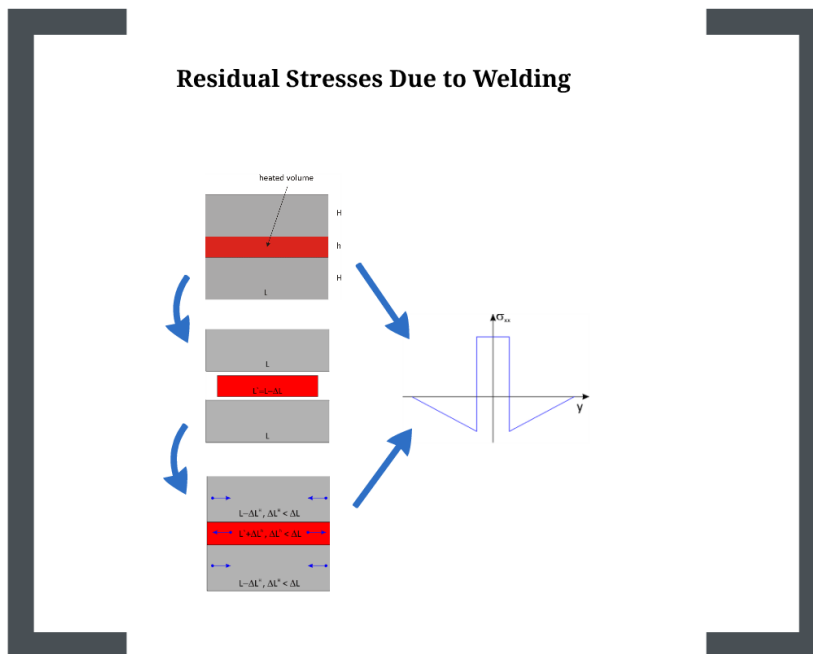








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## Formation of residual stresses

Mechanical 

Thermal 

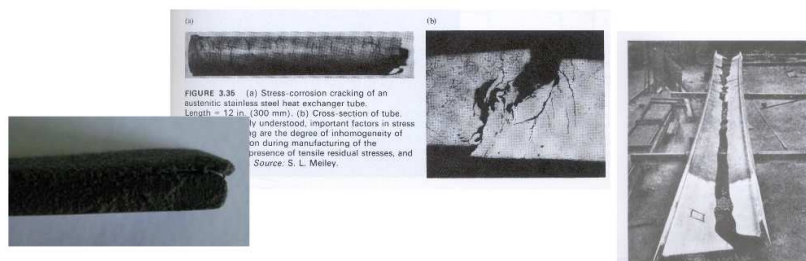
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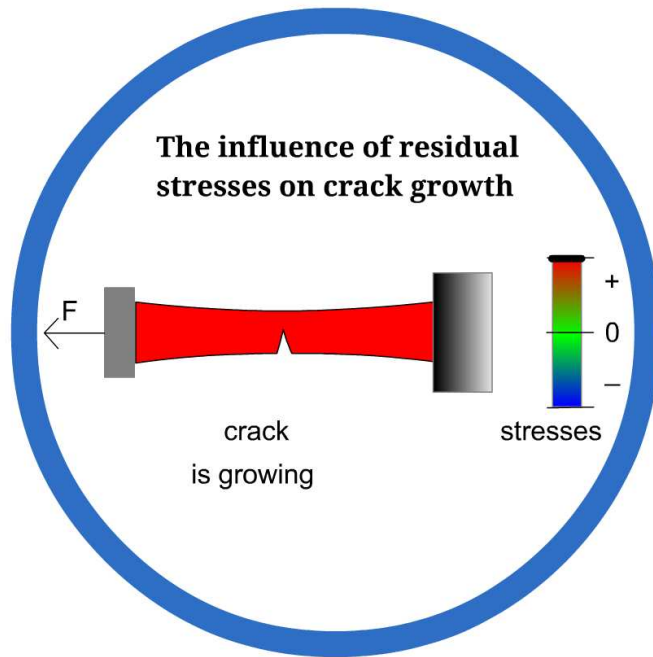
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## Effect of Residual Stresses

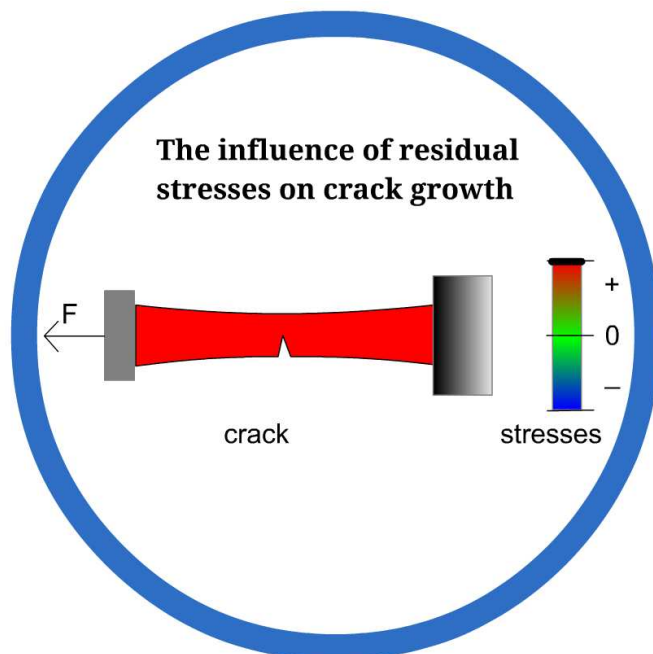
1. Distortion
2. Low cycle and high cycle fatigue performance
3. Stress corrosion cracking (SCC) and hydrogen initiated cracking (HIC)
4. Reduce buckling strength
5. Crack initiation and propagation. (Damage tolerance)



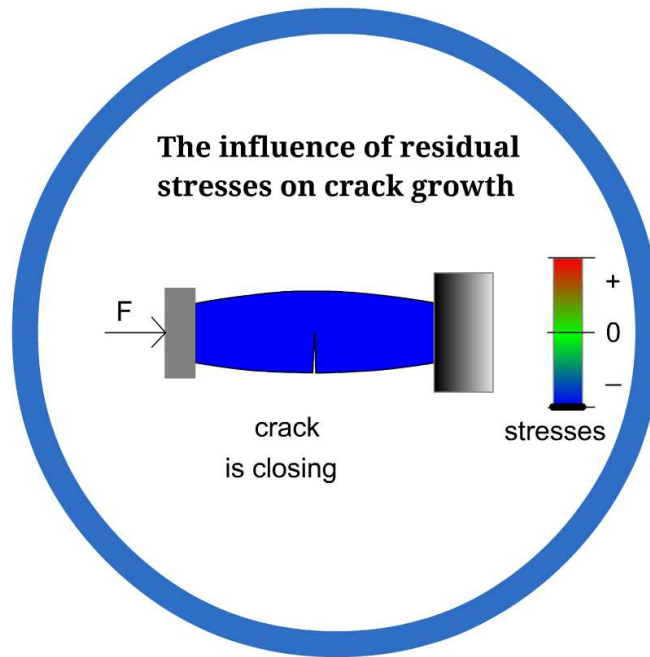
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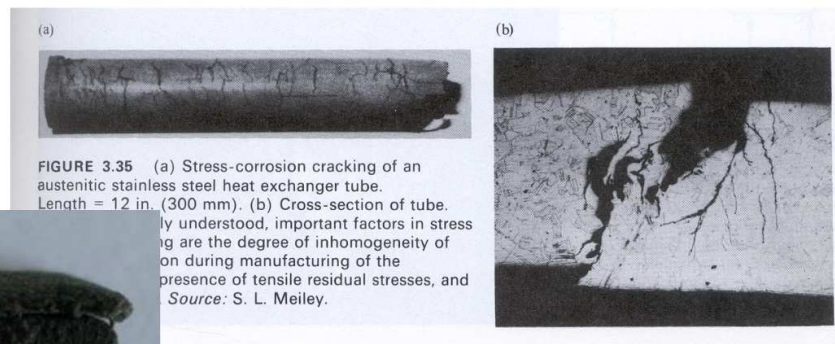
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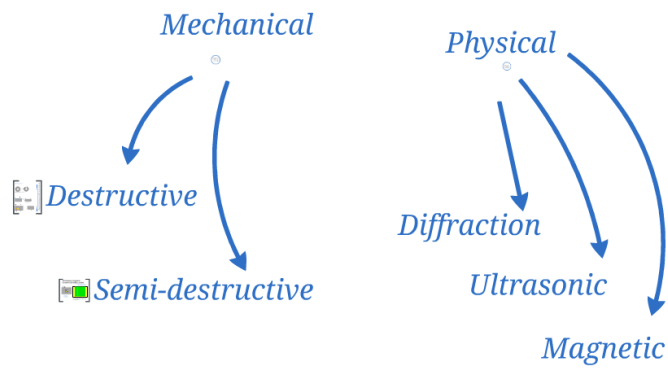


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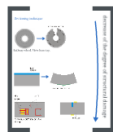
# Residual Stress Measurement Methods



Physical methods are based on measurements of electromagnetic, optical and other physical phenomena in the residual stress zone

Mechanical techniques are called Stress-relaxation methods, which analyze the stress-relaxation produced in a metal part when material is removed. By measuring the deformation caused by the relaxation, the values of the residual stresses present in the part before the metal was removed can be determined by analyzing the successive state of equilibrium

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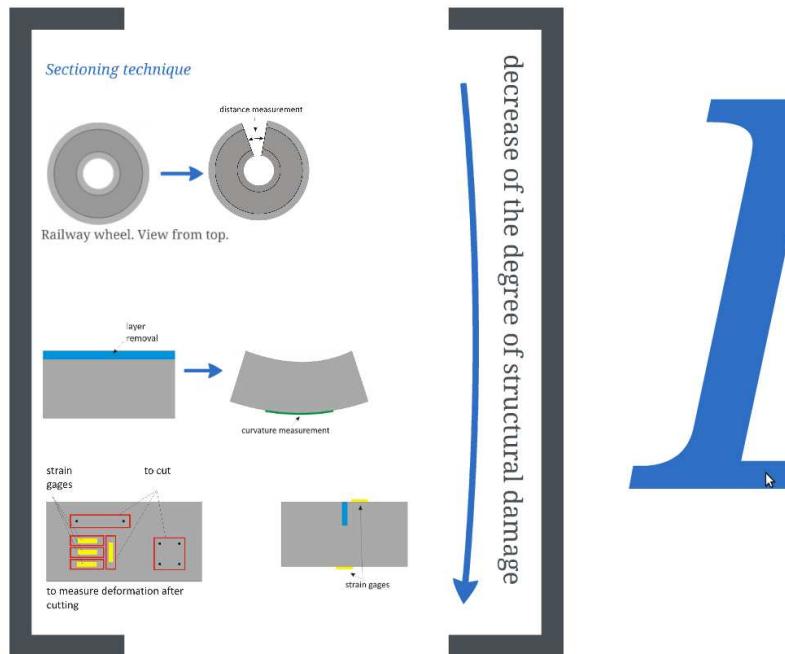
*Destructive*

4

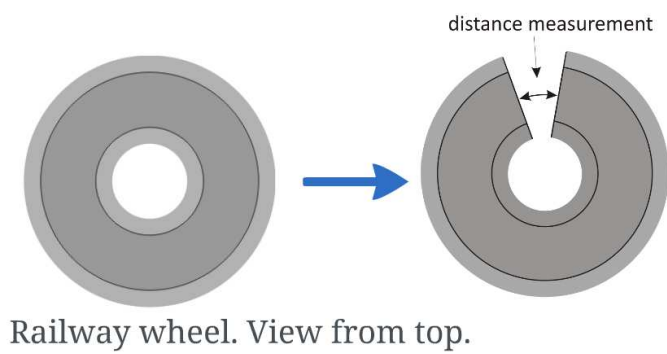


*Semi destructive*

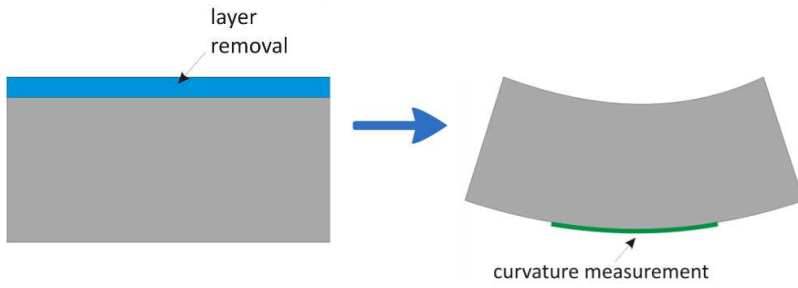




*Sectioning technique*

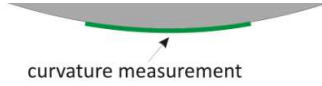


Railway wheel. View from top.

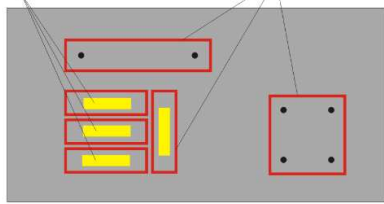


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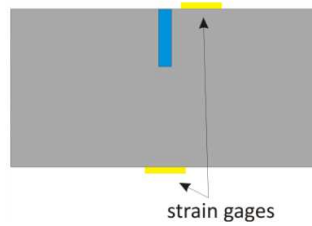
strain gages to cut



strain gages to cut



to measure deformation after cutting



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**Determination of Residual stresses by hole-drilling method**

*FEM simulation*

drilled hole    strain gages

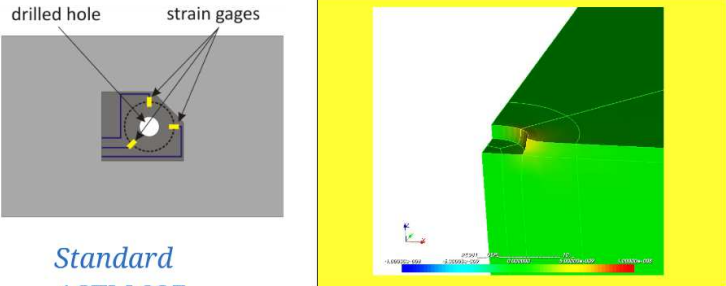
*Standard  
ASTM 837*

Displacements and strains in the vicinity of the drilled holes in the stressed material

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**Determination of Residual stresses by hole-drilling method**

*FEM simulation*



drilled hole      strain gages

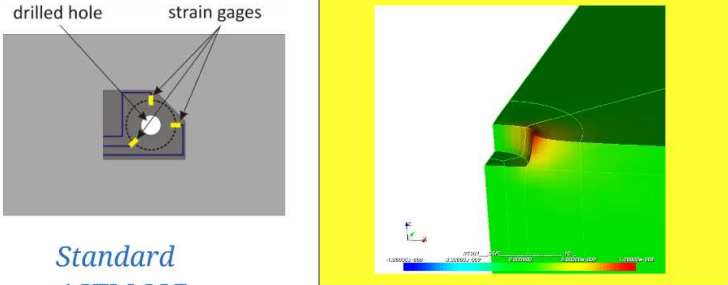
*Standard  
ASTM 837*

Displacements and strains in the vicinity of the drilled holes in the stressed material

The image shows a schematic of a hole-drilling method on the left, with a central hole and four strain gages arranged around it. To the right is a 3D FEM simulation of a similar hole in a stressed material, with a color scale indicating stress levels from blue (low) to red (high). The simulation shows high stress concentrations at the edges of the hole.

**Determination of Residual stresses by hole-drilling method**

*FEM simulation*



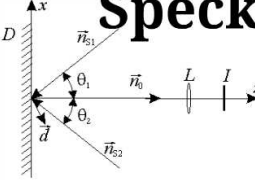
drilled hole      strain gages

*Standard  
ASTM 837*

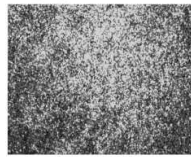
Displacements and strains in the vicinity of the drilled holes in the stressed material

This slide is identical to the one above, showing a schematic of the hole-drilling method and a corresponding 3D FEM simulation of stress distribution around a hole in a stressed material.

## Speckle-interferometry



The optical scheme of a speckle-interferometer:  
D - surface of the object,  
I - image plane



A typical speckle pattern formed by coherent illumination of a diffuse surface

$$I_1 = J_1 + J_2 + 2\sqrt{J_1 J_2} \cos(\Psi) \tag{1}$$

$$I_2 = J_1 + J_2 + 2\sqrt{J_1 J_2} \cos(\Psi + \Delta\varphi(\vec{d})) \tag{2}$$

$$\rho(\Delta\varphi_c) = \frac{\langle I_1 I_2 \rangle - \langle I_1 \rangle \langle I_2 \rangle}{\sigma_{I_1} \sigma_{I_2}} \quad \sigma_{I_2} = \sqrt{\langle I_2^2 \rangle - \langle I_2 \rangle^2} \quad \sigma_{I_1} = \sqrt{\langle I_1^2 \rangle - \langle I_1 \rangle^2} \tag{3}$$

$$\rho_{I_1 I_2} = \frac{1 + \cos(\Delta\varphi(\vec{d}))}{2} \tag{4}$$

$$I = a + b \cos(\Delta\varphi) \tag{5}$$

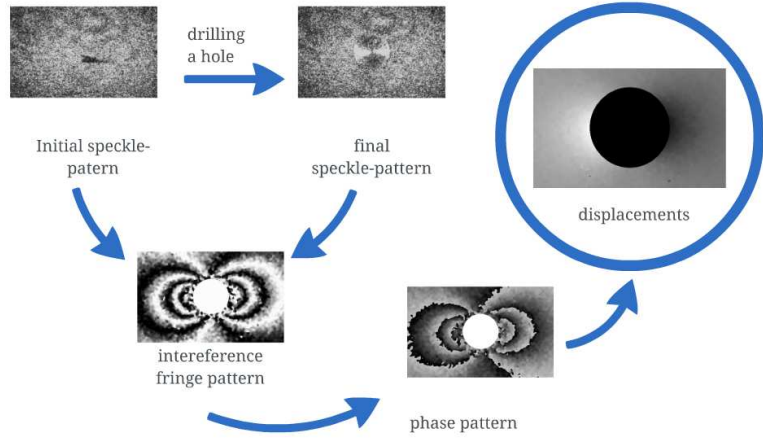
$$\Delta\varphi(\vec{d}) = \frac{2\pi(\vec{n}_0 - \vec{n}_{z1}) \cdot \vec{d}}{\lambda} - \frac{2\pi(\vec{n}_0 - \vec{n}_{z2}) \cdot \vec{d}}{\lambda} = \frac{2\pi(\vec{n}_{z2} - \vec{n}_{z1}) \cdot \vec{d}}{\lambda} \tag{6}$$

$$\vec{n}_{z2} - \vec{n}_{z1} = (\sin\theta_1, 0, \cos\theta_1)^T - (-\sin\theta_1, 0, \cos\theta_1)^T = 2\sin\theta_1(1, 0, 0)^T \tag{7}$$

$$\Delta\varphi(\vec{d}) = \frac{2\pi(\vec{n}_{z2} - \vec{n}_{z1}) \cdot \vec{d}}{\lambda} = \frac{4\pi \sin\theta_1(1, 0, 0) \cdot (d_x, d_y, d_z)^T}{\lambda} = \frac{4\pi d_x \sin\theta_1}{\lambda} \tag{8}$$

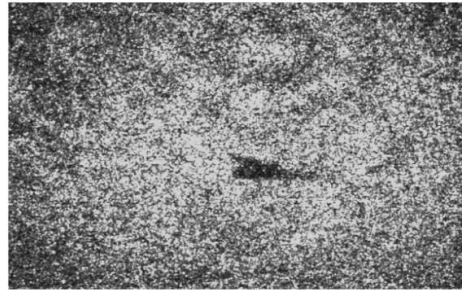
$$d_x = \frac{\lambda}{4\pi \sin\theta_1} \Delta\varphi(\vec{d}) \tag{9}$$

## Displacement measuring using ESPI-method



The diagram illustrates the ESPI method process:

- Initial speckle-pattern** and **final speckle-pattern** are obtained after **drilling a hole**.
- The two speckle patterns are combined to form an **interference fringe pattern**.
- The interference pattern is processed to create a **phase pattern**.
- The phase pattern is used to measure **displacements**.



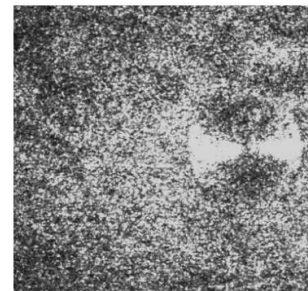
drilling  
a hole



Initial speckle-  
pattern



drilling  
a hole

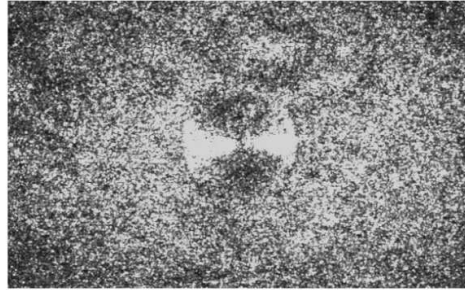


Initial speckle-  
pattern

final  
speckle-pa



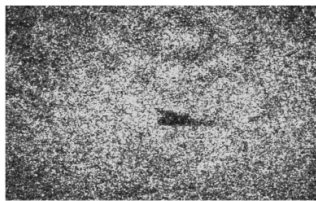
drilling  
hole



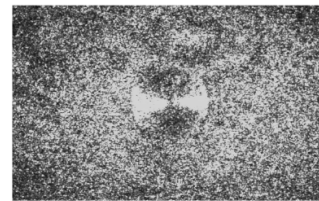
final  
speckle-pattern



# using ESPI-me



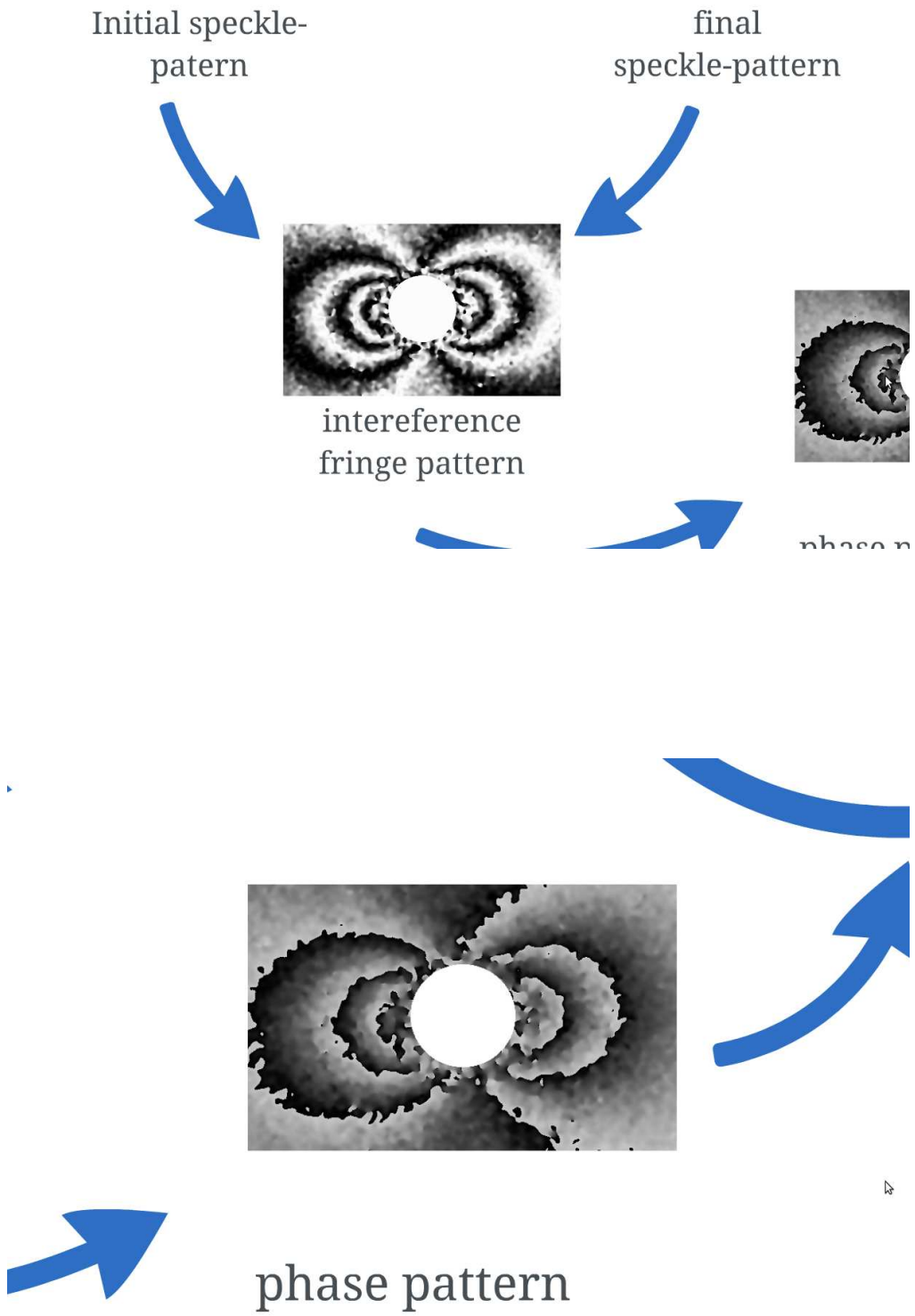
drilling  
a hole



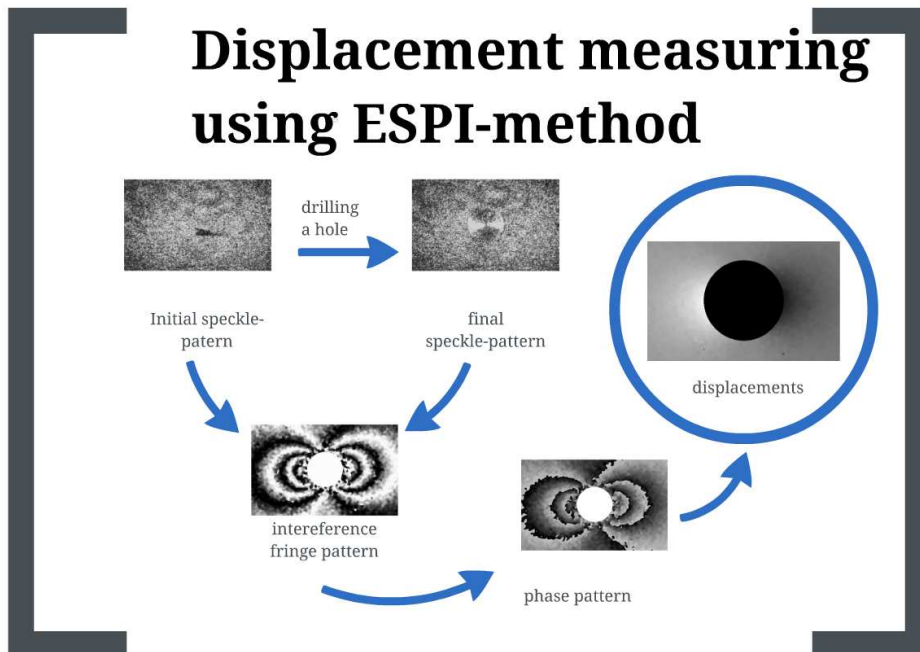
Initial speckle-  
pattern

final  
speckle-pattern









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## Residual stresses calculation using displacements data around a hole

$$u_r(r, \theta) = A(\sigma_{xx} + \sigma_{yy}) + B[(\sigma_{xx} - \sigma_{yy}) \cos 2\theta + 2\tau_{xy} \sin 2\theta] \quad (1)$$

$$u_\theta(r, \theta) = C[(\sigma_{xx} - \sigma_{yy}) \sin 2\theta - 2\tau_{xy} \cos 2\theta] \quad (2)$$

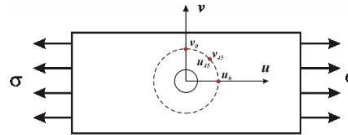
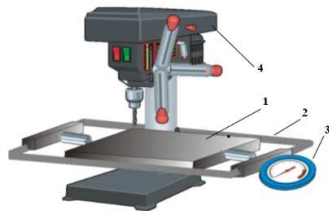
$$u_x(r, \theta) = u_r(r, \theta) \cos \theta - u_\theta(r, \theta) \sin \theta \quad (3)$$

$$u_x(\theta) \Big|_{r=2.5r_0} = F(\theta)\sigma_{xx} + G(\theta)\sigma_{yy} + H(\theta)\tau_{xy} \quad (4)$$

$$\begin{bmatrix} F(\theta_1) & G(\theta_1) & H(\theta_1) \\ F(\theta_2) & G(\theta_2) & H(\theta_2) \\ F(\theta_3) & G(\theta_3) & H(\theta_3) \end{bmatrix} \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \tau_{xy} \end{bmatrix} = \begin{bmatrix} u_x(\theta_1) \\ u_x(\theta_2) \\ u_x(\theta_3) \end{bmatrix} \quad (5)$$

4

# Determination of coefficients A, B и C



$$\bar{A} = \frac{u_0 + v_0}{2\sigma} = \frac{u_{0x} + v_{0y}}{\sqrt{2}\sigma} \quad (1)$$

$$\bar{B} = \frac{u_0 - v_0}{2\sigma} \quad (2)$$

$$\bar{C} = \frac{u_{0y} - v_{0x}}{\sqrt{2}\sigma} \quad (3)$$

4



$$u_x(\theta) = -u_0 - F(\theta)\sigma_x + G(\theta)\sigma_y + H(\theta)\tau_{xy} \quad (4)$$

$$\begin{matrix} F(\theta_1) & G(\theta_1) & H(\theta_1) \\ F(\theta_2) & G(\theta_2) & H(\theta_2) \\ F(\theta_3) & G(\theta_3) & H(\theta_3) \end{matrix} \begin{matrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{matrix} = \begin{matrix} u_x(\theta_1) \\ u_x(\theta_2) \\ u_x(\theta_3) \end{matrix} \quad (5)$$

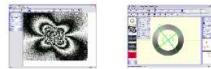
# Determination of residual stresses using speckle-interferometry method

Equipment for determination of RS



- 1 - speckle interferometer; 2 - fiber;
- 3 - drilling device; 4 - laser; 5 - notebook

Software for determination of RS



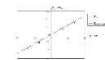
User interface of the Tringe Viewer software for ESPI device controlling and preliminary image processing.

User interface of the Tringe Editor software for calculation of residual stresses

Evaluation of the accuracy of the displacement measurements and RS determination



Problem about the bending of a cantilever beam with a fixed end by a force applied to a free end



Comparison of theoretical and experimental determination of residual stresses

# Determination of residual stresses in a railway wheel using ESPI-HD method



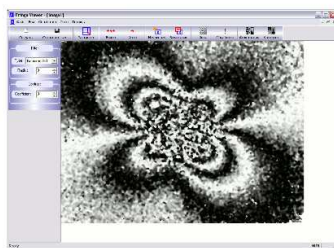
## Equipment for determination of RS



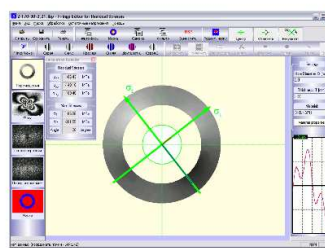
1 - speckle-interferometer; 2 - fiber;  
3 - drilling device; 4 - laser; 5 - notebook

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## Software for determination of RS



User interface of the 'Fringe Viewer' software for ESPI-device controlling and preliminary image processing.

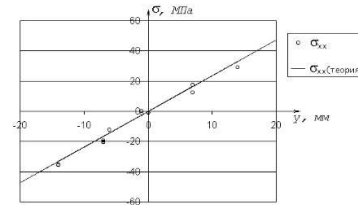
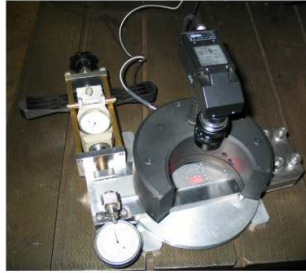


User interface of the 'Fringe Editor' software for calculation of residual stresses

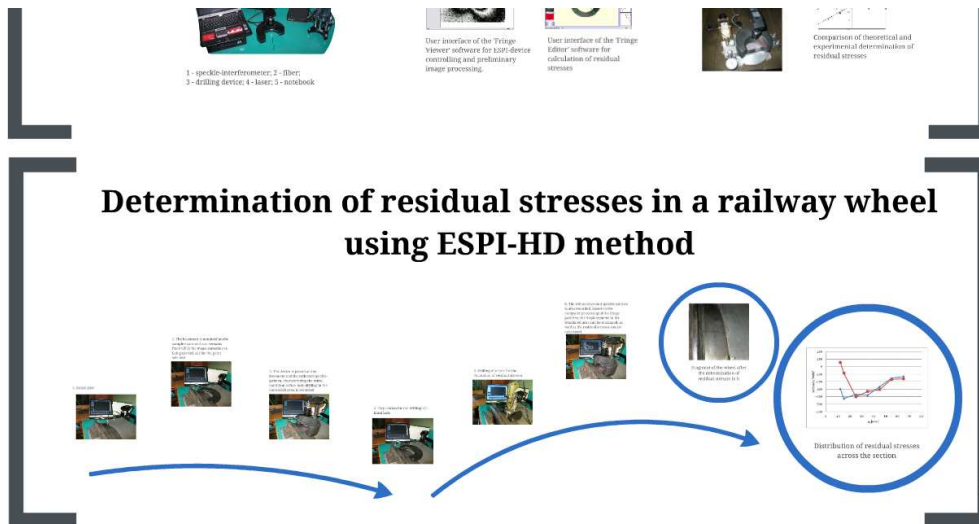
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## Evaluation of the accuracy of the displacement measurements and RS determination

Problem about the bending of a console beam with a fixed end by a force applied to a free end



Comparison of theoretical and experimental determination of residual stresses



1. Initial state



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2. The basement is mounted on the sample examined and remains fixed while the measurements are being carried out for the point selected.



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3. The device is placed on the basement and the reflected speckle-pattern, characterizing the initial condition before hole-drilling in the controlled area, is recorded



4

4. Preparation for the drilling of a blind hole



4

5. Drilling of a hole for the relaxation of residual stresses



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6. The reflected second speckle-pattern is also recorded. Based on the computer processing of the fringe patterns, the displacements in the irradiated area can be evaluated, as well as the residual stresses can be calculated.



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n



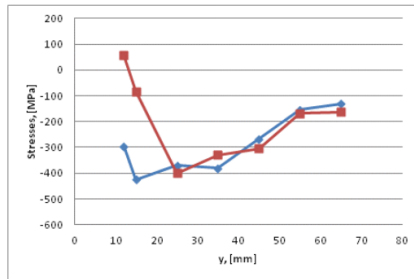
Fragment of the wheel after the determination of residual stresses in it



4



Fragment of the wheel after the determination of residual stresses in it



Distribution of residual stresses across the section

4





### Determination of residual stresses in a railway wheel using ESPI-HD method

1 - speckle-interferometer; 2 - fiber; 3 - drilling device; 4 - laser; 5 - notebook

User interface of the Tringe Viewer software for ESPI-device controlling and preliminary image processing.

User interface of the Tringe Editor software for calculation of residual stresses.

Comparison of theoretical and experimental determination of residual stresses.

Typical distribution of residual stress over the surface.

General view of the optical device, including: illuminator, camera, microscope, detector for camera, 12-bit camera, computer, video card, 17" monitor.

Typical view of the wheel of a railway wheel.

Distribution of residual stresses across the section.

### Residual Stress Measurement Methods

**Mechanical**

- Destructive
- Semi-destructive

**Physical**

- Diffraction
- Ultrasonic
- Magnetic

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### Residual stresses calculation using displacements data around a hole

$\sigma_{xx} = \frac{E}{2(1-\nu^2)} \left[ \frac{1}{r} \frac{d}{dr} \left( r \frac{d}{dr} (u) \right) + \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} (v) \right) \right]$   
 $\sigma_{\theta\theta} = \frac{E}{2(1-\nu^2)} \left[ \frac{1}{r} \frac{d}{dr} \left( r \frac{d}{dr} (u) \right) - \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} (v) \right) \right]$   
 $\tau_{r\theta} = -\frac{E}{2(1+\nu)} \left[ \frac{1}{r} \frac{d}{dr} (v) + \frac{d}{dr} \left( \frac{u}{r} \right) \right]$

$\sigma_{xx} = \frac{E}{2(1-\nu^2)} \left[ \frac{1}{r} \frac{d}{dr} \left( r \frac{d}{dr} (u) \right) + \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} (v) \right) \right]$   
 $\sigma_{\theta\theta} = \frac{E}{2(1-\nu^2)} \left[ \frac{1}{r} \frac{d}{dr} \left( r \frac{d}{dr} (u) \right) - \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} (v) \right) \right]$   
 $\tau_{r\theta} = -\frac{E}{2(1+\nu)} \left[ \frac{1}{r} \frac{d}{dr} (v) + \frac{d}{dr} \left( \frac{u}{r} \right) \right]$

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 $\tau_{r\theta} = -\frac{E}{2(1+\nu)} \left[ \frac{1}{r} \frac{d}{dr} (v) + \frac{d}{dr} \left( \frac{u}{r} \right) \right]$

**Software for determination of RS**

**Evaluation of the accuracy of the displacement measurements using ESPI-interferometry**

### Stress gradient over the surface

Typical distribution of residual stress over the surface.

General view of the optical device, including: illuminator, camera, microscope, detector for camera, 12-bit camera, computer, video card, 17" monitor.

Typical view of the wheel of a railway wheel.

Typical distribution of residual stress over the surface.

Local distribution of residual stress across the surface.

Typical distribution of residual stress over the surface.

Local distribution of residual stress across the surface.

Typical distribution of residual stress over the surface.

Local distribution of residual stress across the surface.

Typical distribution of residual stress over the surface.

Local distribution of residual stress across the surface.

### Shearography

The optical set-up of shearography.

Gives possibility to measure drifts or slowly or d-(1 + cos(α)) drifts + static drifts where α - angle between directions of illumination and observation.

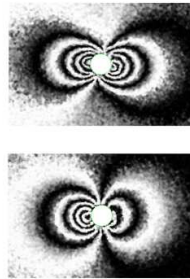
Shearography allows determine the numerical differentiation advantage is a low sensitivity.

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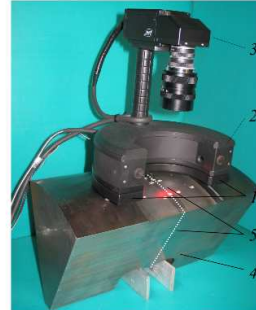
### Quality control of a spot resistance weld

1 - general view; 2,3 - typical in testing areas, respective change in derivative from structures along the selected distinguishes and shown by

# Stress gradient over the surface



Typical symmetrical (top) and non-symmetrical (bottom) fringe patterns in the vicinity of a drilled blind hole in a stressed material

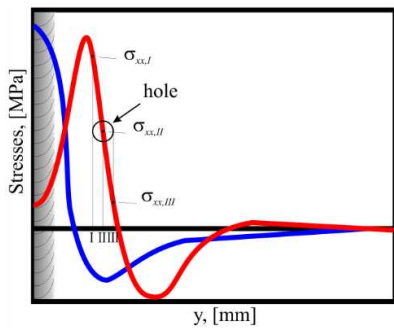


General view of the optical device, including: 1 – basement; 2 – removable module of speckle-interferometer; 3 – CCD-camera; 4 – sample of a welded joint; 5 – a weld seam.

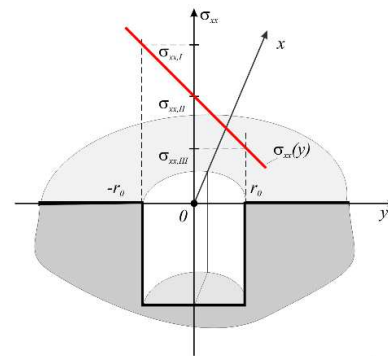
$\uparrow \sigma_x$

stressed material

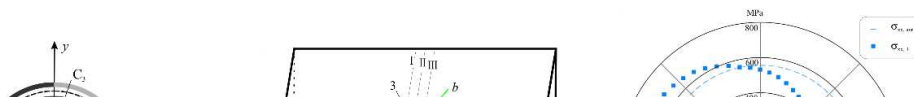
weld seam.



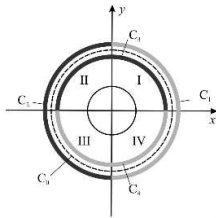
Typical distributions of longitudinal residual stresses versus distance from the weld center line.



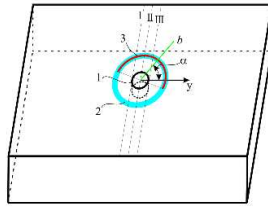
Local distribution of residual stresses across the drilled hole



Typical distributions of longitudinal residual stresses versus distance from the weld center line.

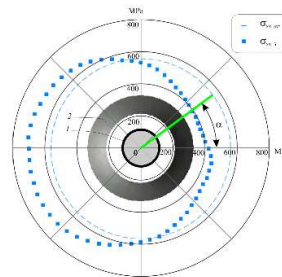


Scheme of an area division into sectors for investigation of the stresses' gradient in the hole zone



Scheme of points where measured displacements are used for evaluation of stress gradient over the surface: 1 – drilled hole; 2 – circle; 3 – semicircle corresponding to angle  $\alpha$ .

Local distribution of residual stresses across the drilled hole

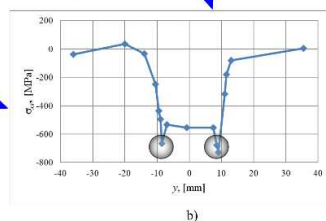
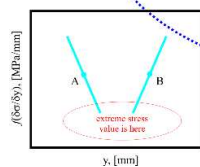
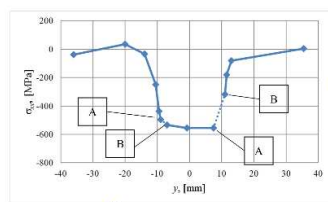


Graphical presentation of the stresses shows their deviations from the averaged value: 1 – hole; 2 – measured displacements are presented in the form of a grayscale values.



semicircle corresponding to angle  $\alpha$ .

of a grayscale values.



Distribution of circumferential residual stresses in the surface welded rotor obtained by: a) – conventional method of determination of residual stresses; b) – ESPI-HD – method with the technology of evaluating the stress gradient over the surface

The use of the ESPI-HD method makes it possible to increase the accuracy of residual stress determination and also gives an additional opportunity of the stress gradient assessment on the basis of the drilled out hole. The high sensitivity of the device enables to conduct the investigations of the stressed state on a small base (from 0.5 mm) without any loss of the experiment accuracy. The procedure of residual stress determination, compactness of the equipment and efficiency of the computer processing of the optical information open the new possibilities for examining the structures under the laboratory and industrial conditions.

4

**Determination of Residual stresses**

**Formation of residual stresses**

- Mechanical [σ]
- Thermal [σ]
- Metallurgical
- Chemical

**Effect of Residual Stresses**

1. Increase of strength and high cycle fatigue performance
2. Residual stresses change the crack propagation resistance (R-curve)
3. Stress relaxation (creep)
4. Crack initiation (plasticity, cleavage, corrosion)

**Residual Stress Measurement Methods**

- Mechanical: Strain gauges, Hole drilling, Slitting disc
- Physical: X-ray diffraction, Neutron diffraction, Ultrasonic
- Semi-destructive: Photoelasticity, ESPI

**Stress gradient over the surface**

**Speckle-interferometry**

Principle of operation of speckle interferometry

Mathematical relationships

Speckle pattern

**Displacement measuring using ESPI-method**

**Residual stresses calculation using displacements data around a hole**

Calculation of residual stresses

Mathematical relationships

**Determination of coefficients A, B or C**

**Determination of residual stresses using speckle-interferometry method**

Equipment for determination of A, B or C

ESPI method for determination of A, B or C

Displacement data processing for the determination of residual stresses

**Determination of residual stresses in a railway wheel using ESPI-HD method**

The use of the ESPI-HD method makes it possible to increase the accuracy of residual stress determination and also gives an additional opportunity of the stress gradient assessment on the basis of the drilled out hole. The high sensitivity of the device enables to conduct the investigations of the stressed state on a small base (from 0.5 mm) without any loss of the experiment accuracy. The procedure of residual stress determination, compactness of the equipment and efficiency of the computer processing of the optical information open the new possibilities for examining the structures under the laboratory and industrial conditions.

### Non destructive testing

**...ent over the surface**

#### Shearography for NDT

The optical set-up of shearography

Gives possibility to measure  $dw/dx$  or  $dw/dy$  or  $d=(1 + \cos(\alpha)) dw/dx + \sin(\alpha) du/dx$  where  $\alpha$  - angle between directions of illumination and observation

Shearography allows determination of deformation without the numerical differentiation of data. In addition, its main advantage is a low sensitivity to vibrations.

#### Shearographic unit

General view of a shearographic unit: 1 - laser, 2 - shearographic module, 3 - computer.

#### Quality control of a three-layer made by a spot resistance welding

1 - general view, 2,3 - optical deformation patterns obtained by testing areas, respectively, with and without defects, 4,5 - change in direction from side of plane of observation of observation along the selected sections (curves of defects are distinguishable and checked by arrows)

#### Quality control of glass-reinforced plastic tubular element

1 - general view, 2,3 - optical deformation patterns obtained by testing areas, respectively, with and without defects, 4,5 - change in direction from side of plane of observation of observation along the selected sections (curves of defects are distinguishable and checked by arrows)

The non destructive quality control of elements and structures using the electronic shearography method showed that the technology allows revealing different types of defects (lack of penetration, cracks, lack of adhesion and other imperfections of materials, which cause a local concentration of deformations under loading)

4

## Shearography for NDT

The optical set-up of shearography

Gives possibility to measure  $dw/dx$  or  $dw/dy$  or  $d=(1 + \cos(\alpha)) dw/dx + \sin(\alpha) du/dx$  where  $\alpha$  - angle between directions of illumination and observation

heating

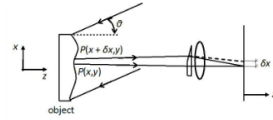
composite layer

pipe

Shearography allows determination of deformation without the numerical differentiation of data. In addition, its main advantage is a low sensitivity to vibrations.

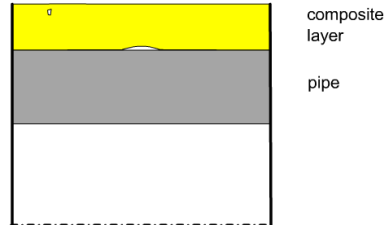
4

## Shearography for NDT



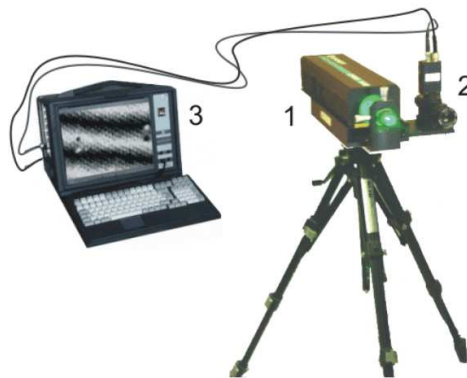
The optical set-up of shearography

Gives possibility to measure  $dw/dx$  or  $dw/dy$  or  $d = (1 + \cos(\theta)) dw/dx + \sin(\theta) du/dx$  where  $\theta$  - angle between directions of illumination and observation



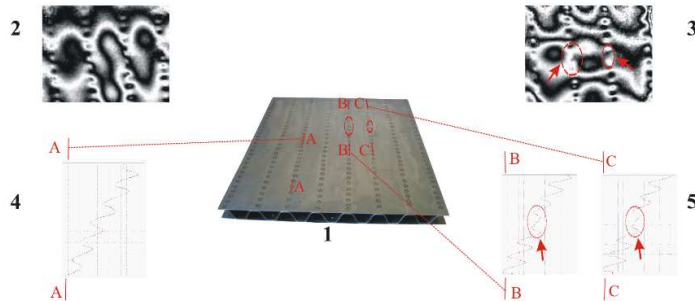
Shearography allows determination of deformation without the numerical differentiation of data. In addition, its main advantage is a low sensitivity to vibrations.

## Shearographic unit



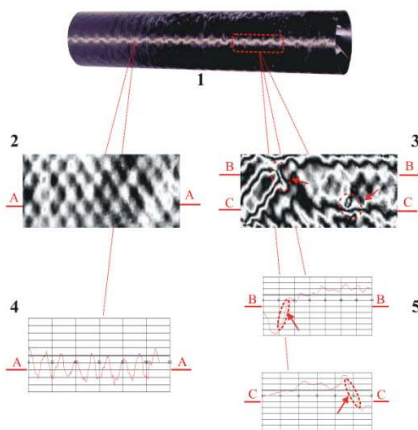
General view of a shearographic unit: 1 – laser, 2 – shearographic module; 3 – computer.

### Quality control of a three-layer made by a spot resistance welding



1 – general view; 2,3 – typical interference pattern obtained in testing areas, respectively, with and without defects; 4,5 – change in derivative from out-of-plane displacements of structures along the selected sections (zones of defects are distinguishes and shown by arrows)

### Quality control of glass-reinforced plastic tubular element



1 – general view; 2,3 – typical interference pattern obtained in testing areas, respectively, with and without defects; 4,5 – change in derivative from out-of-plane displacements of structures along the selected sections (zones of defects are distinguishes and shown by arrows)

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