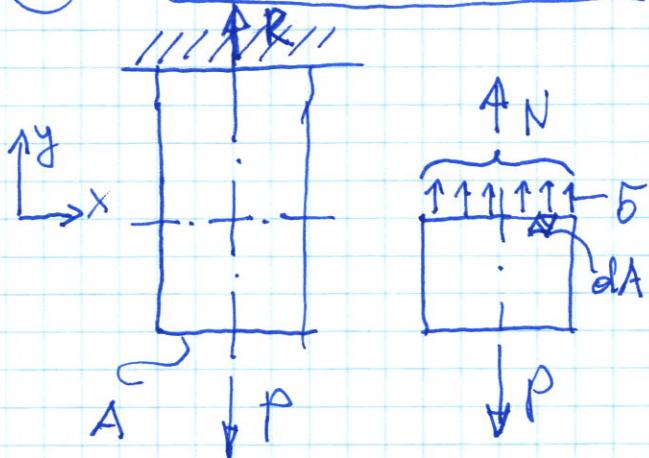


Tension, compression. Introduction

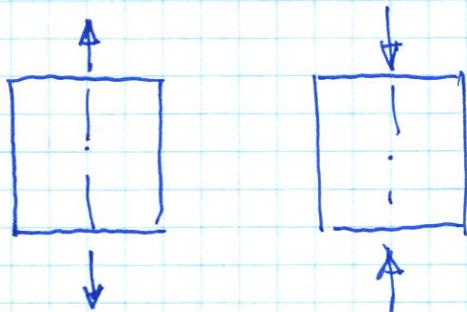
1. static conditions



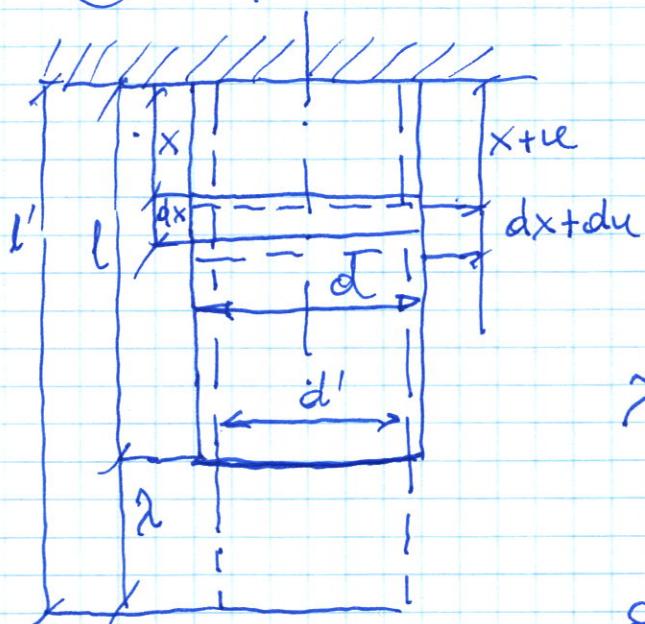
$$\sum P_{iy} = P - N = 0$$

$$\int \sigma \cdot dA = N$$

Agreement as to the sign of force



2. geometric conditions



$$\frac{du}{dx} = \epsilon \quad (\text{def})$$

axial strain - longitudinal strain

$$\lambda = \Delta l = l' - l$$

λ elongation

$$\lambda = u_{x=0} = \int_0^l \epsilon \cdot dx = \epsilon \cdot l$$

$$\epsilon = \frac{\lambda}{l} = \frac{\Delta l}{l}$$

$$\epsilon = \frac{d' - d}{d} \quad (\text{for tension})$$

$$d > d' \quad \epsilon' < 0$$

transverse strain
(latitudinal strain)

3. Physical conditions, Hooke's law

$$E = \sigma \frac{1}{\epsilon} \quad , \quad \Delta l = \frac{P \cdot l}{E \cdot A}$$

$$\sigma = -\gamma \cdot \epsilon \quad \frac{1}{6} < \gamma < \frac{1}{2}$$

$\nu \approx 0,3$
(for steel)

$$\sigma = \frac{N}{A}$$

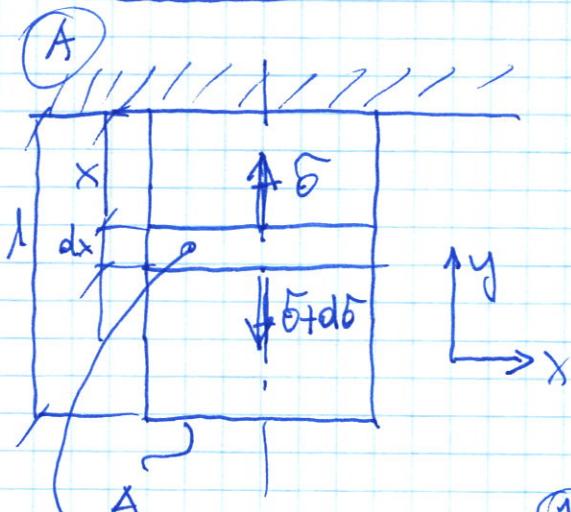
$$\lambda = \Delta l = \int_0^l \epsilon dx = \int_0^l \frac{\sigma}{E} \cdot dx = \int_0^l \frac{N}{A \cdot E} dx = \frac{N \cdot l}{E \cdot A}$$

$$\Delta l = \lambda = \frac{N \cdot l}{E \cdot A}$$

$E \cdot A$ - stiffness for tension/compression

$\frac{EA}{l}$ - unit stiffness for tension/compression

Tension . Influence of weight on stresses.



Assumptions: $P, A = \text{const}, l, \gamma$
to determine: $\sigma(x), \epsilon(x) - ?$
 γ - specific gravity / specific weight

static equation

$$\textcircled{1} \quad \sum P_i y = A(\sigma + d\sigma) + A \cdot \gamma \cdot dx - A \cdot \sigma = 0$$

$$A \cdot \sigma + A \cdot d\sigma + A \cdot \gamma \cdot dx - A \cdot \sigma = 0 \quad | : A$$

$$d\sigma = -\gamma \cdot dx$$

$$\boxed{\sigma = -\gamma \cdot x + C}$$

$$\sigma = \frac{P}{A} + \gamma \cdot l \quad (\max)$$

$$\sigma = \frac{P}{A} \quad (\min)$$

but from static equation

$$\sigma_{x=l} = \frac{P}{A} \Rightarrow \frac{P}{A} = -\gamma \cdot l + C \Rightarrow C = \frac{P}{A} + \gamma \cdot l$$

$$\sigma = -\gamma \cdot x + \frac{P}{A} + \gamma \cdot l \Rightarrow \boxed{\sigma = \frac{P}{A} + \gamma(l-x)}$$

stress state

$$\epsilon = \frac{\sigma}{E} = \frac{1}{E} \left[\frac{P}{A} + \gamma(l-x) \right]$$

$$\Delta l = \int_0^l \epsilon(x) dx = \frac{1}{E} \int_0^l \left[\frac{P}{A} + \gamma(l-x) \right] dx = \frac{1}{E} \left[\frac{P}{A} \cdot x + \gamma \cdot l \cdot x - \frac{\gamma x^2}{2} \right]_0^l$$

$$\Delta l = \frac{1}{E} \left[\frac{P \cdot l}{A} + \gamma \cdot l^2 - \frac{\gamma l^2}{2} \right] = \frac{1}{E} \left[\frac{P \cdot l}{A} + \frac{\gamma l^2}{2} \right]$$

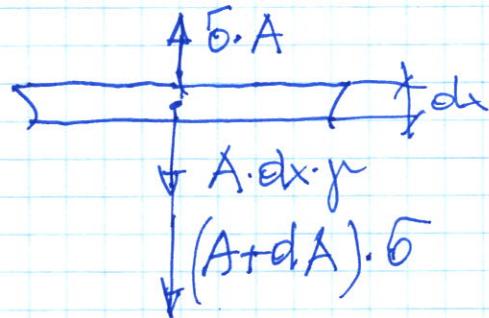
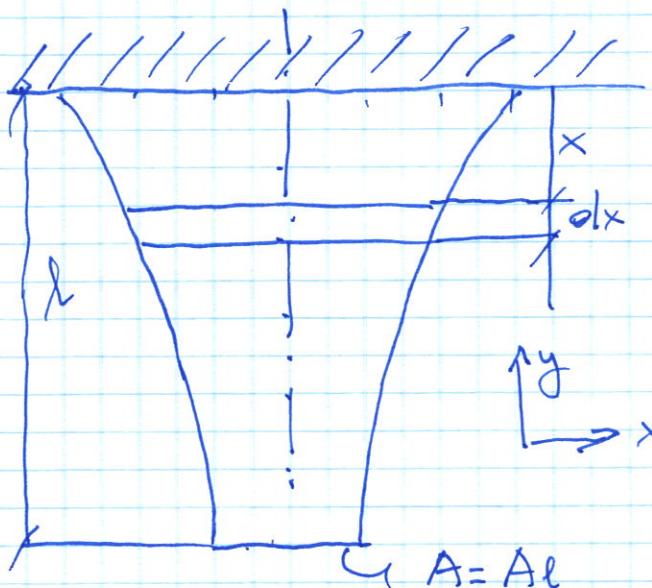
$$\Delta l = \frac{P \cdot l}{E \cdot A} + \frac{\gamma l^2}{2 \cdot E}$$

$$\boxed{\Delta l = \frac{P \cdot l}{E \cdot A} + \frac{Q \cdot l}{2 \cdot E}}$$

but assume that $Q = A \cdot l \cdot \gamma$
↓ weight

(B)

Assumptions: $\ell, P, A_{x=0} = A$ ($B = \text{const}$) μ
to designate: $A(x) - ?$



static equation

$$\textcircled{1} \quad \sum F_{iy} = (A + dA)B + A \cdot \mu \cdot dx - B \cdot A = 0 \\ A \cdot B + dA \cdot B + A \cdot \mu \cdot dx - B \cdot A = 0 \quad | : A \cdot B$$

$$\frac{1}{A} dA = -\frac{\mu}{B} \cdot dx$$

$$\ln A + C = -\frac{\mu}{B} \cdot x$$

$$\text{but } A_{x=0} = A_0 = \frac{P}{B}$$

$$\ln A_0 + C = -\frac{\mu}{B} \cdot 0 \Rightarrow C = -\ln A_0 - \frac{\mu}{B} \cdot 0$$

$$\ln A - \ln A_0 = -\frac{\mu}{B} \cdot l - \frac{\mu}{B} \cdot x$$

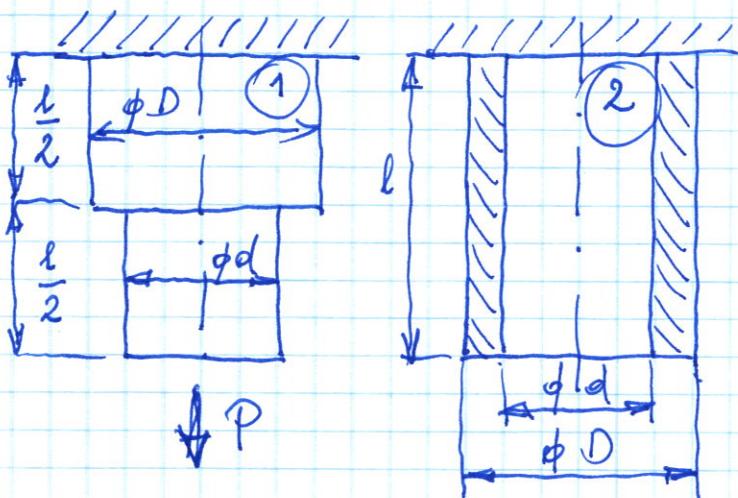
$$\ln \frac{A}{A_0} = -\frac{\mu}{B} (l - x)$$

$$A = A_0 \cdot e^{-\frac{\mu}{B} (l - x)}$$

-A-

Ex. 1e

Compare the stiffnesses of two bars



$$\frac{E_1 \alpha = \frac{d}{D} = 0.8, (P), D}{C = \frac{EA}{l} - 2} \\ C_1, C_2 - ? \\ C - \text{unit stiffness}$$

$$C = \frac{P}{\Delta l} \quad \Delta l = \frac{P \cdot l}{EA} \\ C = \frac{R \cdot EA}{R \cdot l} = \frac{EA}{l} \Rightarrow \text{unit stiffness}$$

(A) Elongation Δl_1 (for bar ①)

$$\Delta l = \frac{P \cdot \frac{l}{2}}{E \frac{\pi d^2}{4}} + \frac{P \cdot \frac{l}{2}}{D^2 \cdot \frac{\pi D^2}{4}} = \frac{4P \cdot l}{2\pi E d^2} + \frac{4P \cdot l}{2\pi E D^2} = \frac{2PL}{\pi E} \left(\frac{1}{d^2} + \frac{1}{D^2} \right)$$

$$\Delta l_1 = \frac{2PL}{\pi E} \frac{1}{D^2}$$

$$\text{and } C_1 = \frac{P}{\Delta l_1} = \frac{\pi E \alpha^2 D^2}{2L(d^2 + D^2)} = \frac{\pi E \alpha^2 D^2 \cdot D^2}{2L D^2 (1 + \alpha^2)} = \frac{\pi E \alpha^2 D^2}{2L(1 + \alpha^2)}$$

(B) Elongation Δl_2 (for bar/tube ②)

$$\Delta l_2 = \frac{P \cdot l}{E \frac{\pi (D^2 - d^2)}{4}} = \frac{4 \cdot P \cdot l}{\pi E (D^2 - d^2)} \\ C_2 = \frac{P}{\Delta l_2} = \frac{\pi E (D^2 - \alpha^2 D^2)}{4l} = \frac{\pi E D^2 (1 - \alpha^2)}{4l}$$

$$(C) K = \frac{C_1}{C_2} = \frac{\pi E \alpha^2 D^2}{2L(1 + \alpha^2)} \cdot \frac{4L}{\pi E D^2 (1 - \alpha^2)} = \frac{2\alpha^2}{1 - \alpha^2}$$

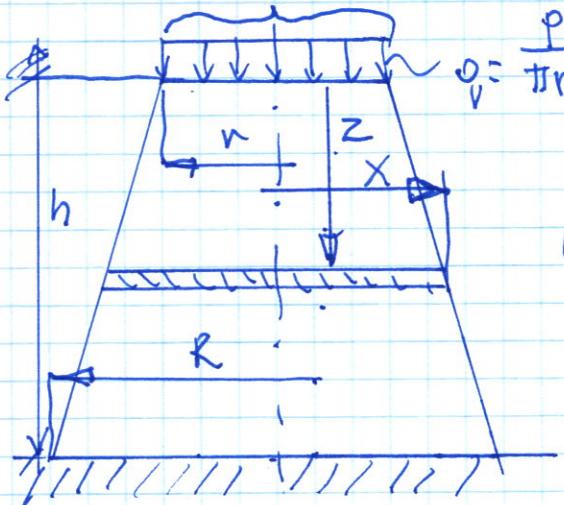
$$\text{for } \alpha = 0.8 \quad K = \frac{2 \cdot 0.8^2}{1 - 0.8^2} = 2.17$$

(D) for which K value - the unit stiffnesses will be identical

$$K = \frac{2\alpha^2}{1 - \alpha^2} = 1 \rightarrow \alpha^4 + 2\alpha^2 - 1 = 0 \quad \alpha^2 = z \\ 2z^2 + 2z - 1 = 0$$

$$z_1 = \frac{-2 + 2\sqrt{2}}{2} = \sqrt{2} - 1 = 0.41 \quad \Delta = h + 4 = 8 \quad T\Delta = 2\sqrt{2} \\ \hookrightarrow \alpha = 0.643$$

Ex. p Truncated cone, weight effect



$$\frac{P}{\pi r^2} \cdot h, R, r, \rho, P$$

$\times 5 \text{ min} - ?$

Note: for rising z , both - the weight and the surface area increase

- ① We need to find a relationship between z and x

$$\frac{z}{h} = \frac{x-r}{R-r} \Rightarrow x = r + \frac{z(R-r)}{h}$$

$$\text{then } dx = \frac{R-r}{h} dz \Rightarrow dz = \frac{h}{R-r} dx$$

- ② The cross-sectional area of radius x is affected by the weight $G(x)$

$$G(x) = \pi \rho \int^x_r x^2 dz = \pi \rho \int^x_r x^2 \frac{h}{R-r} dx = \frac{\pi \rho \cdot h}{R-r} \left[\frac{x^3}{3} \right]_r^x =$$

$$= \left(\frac{\pi \rho \cdot h}{3(R-r)} \right) (x^3 - r^3) = Q(x^3 - r^3) \quad | \text{ where } \\ Q = \frac{\pi \rho \cdot h}{3(R-r)} = \text{const}$$

- ③ The stress for radius x

$$\sigma(x) = \frac{P + G(x)}{\pi x^2} = \frac{P + Q(x^3 - r^3)}{\pi x^2}$$

- ④ Extreme of the function $\sigma(x)$

$$\frac{d\sigma(x)}{dx} = \frac{1}{\pi} \left[Q - 2 \left(\frac{P - Qr^3}{x^3} \right) \right] = 0$$

$$\left(\frac{f(x)}{g(x)} \right)' = \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)}$$

$$Q = \frac{2}{x^3} (P - Qr^3) \Rightarrow$$

$$\Rightarrow x^3 = \frac{2}{Q} (P - Qr^3) \Rightarrow x = \sqrt[3]{2 \left(\frac{P}{Q} - r^3 \right)} = \\ \sqrt[3]{\frac{6\rho (R-r)}{\pi \cdot \rho \cdot h} - 2r^3}$$

-7-

but x must be:

- positive (negative doesn't make sense)
- $r \leq x \leq R$

It is easy to notice that x is positive when
 $\rightarrow p > ar^3$

At the same time, for the extremeum to have minimal value (minimum), the second derivative must be greater than zero!

$$\frac{d^2\delta(x)}{dx^2} > 0 !$$

$$\frac{d^2\delta(x)}{dx^2} = \frac{6(p - ar^3)}{\pi x^4}$$

for $p > ar^3$,

$$\frac{d^2\delta(x)}{dx^2} > 0$$

It means, that

$$r \leq x \leq R$$