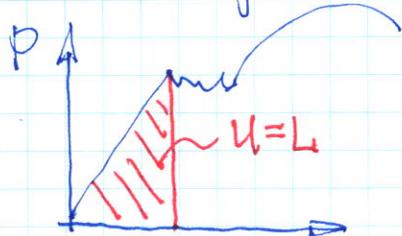


# Canonical Equations of Force Method

(Równanie kanoniczne metody sił)

Canonical equations of force method offer a unified procedure for analysis of statically indeterminate structures of different types. The word "canonical" indicates that these equations are presented in standard or in an orderly fashion form. Very important is that canonical equations of the force method may be presented in a matrix form.



$P_i$  - generalized force

$p_i$  - generalized displacement

for tension-compression

$$L = U = L = \frac{1}{2} P \cdot \Delta l ; \quad \Delta l = \frac{P \cdot l}{E A}$$

$$L = U = L = \frac{1}{2} P \cdot \frac{P L}{E A} = \frac{1}{2} \frac{P^2 L}{E A}$$

(energy is the square function of force)

More generally

$$L_{ii} = U_{ii} = \frac{1}{2} P_i \cdot p_i \quad L = U = \frac{1}{2} \sum_i P_i p_i$$

but  $| p_i = \sum_{k=1}^n P_k \cdot \delta_{ik} |$  in direction "i" (first index)

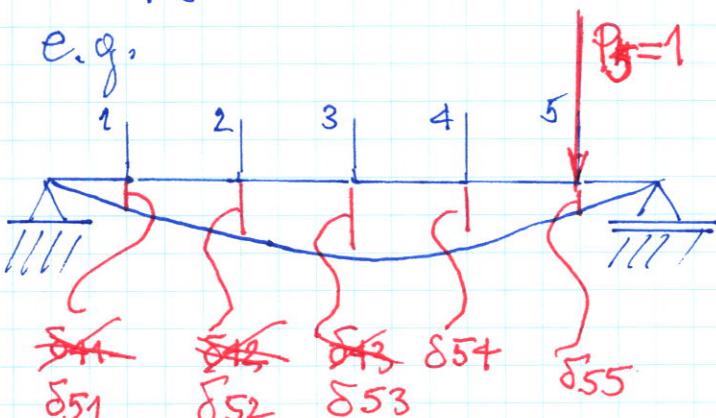
Coefficient  $\delta_{ik}$  is called the unit displacement

since it is caused by unit primary generalized force  $P_k = 1$  ( $k$ -second index)

$\delta_{ik} \iff \begin{array}{c} \text{generalized displacement} \\ \hline \text{generalized force} \end{array}$

unit displacement  
(liczba w przybliżeniu)

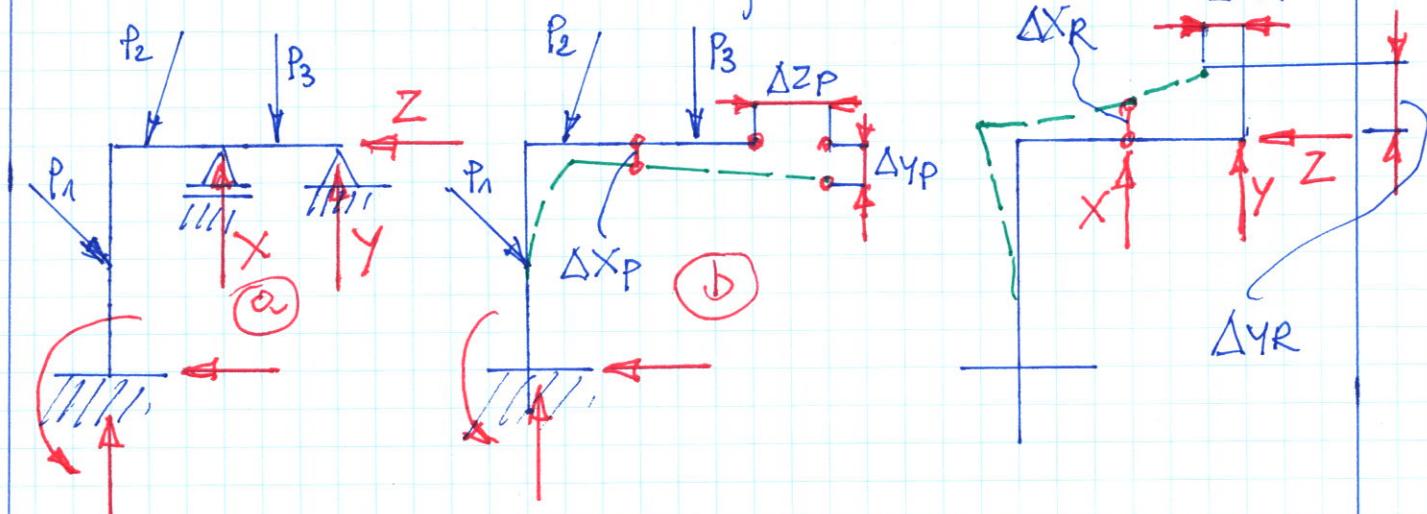
e.g.



$$\delta_{51} = \delta_{15}$$

$$\delta_{ik} = \delta_{ki}$$

Let us consider a simple redundant structure (hypostatic), such as frame. The number of redundant is 3



$\Delta X_p, \Delta Y_p, \Delta Z_p$  - displacements caused by active forces, respectively:  $P_1, P_2, P_3$  for points where they are hypostatic forces, respectively:  $X, Y, Z$

$\Delta X_R, \Delta Y_R, \Delta Z_R$  - displacements caused by ~~active~~ forces (hypostatic reactions) respectively:  $X, Y, Z$  for points where are these hypostatic reactions

$$U = L = \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n P_i \cdot P_k \cdot \delta_{ik}$$

$$\begin{aligned} U = L &= \frac{1}{2} (X^2 \delta_{xx} + Y^2 \delta_{yy} + Z^2 \delta_{zz} + P_1^2 \delta_{11} + P_2^2 \delta_{22} + P_3^2 \delta_{33}) + \\ &+ X \cdot Y \cdot \delta_{xy} + Y \cdot Z \cdot \delta_{yz} + Z \cdot X \cdot \delta_{zx} + X \cdot P_1 \cdot \delta_{x1} + X \cdot P_2 \cdot \delta_{x2} + X \cdot P_3 \cdot \delta_{x3} \\ &+ Y \cdot P_1 \cdot \delta_{y1} + Y \cdot P_2 \cdot \delta_{y2} + Y \cdot P_3 \cdot \delta_{y3} + Z \cdot P_1 \cdot \delta_{z1} + Z \cdot P_2 \cdot \delta_{z2} + Z \cdot P_3 \cdot \delta_{z3} \\ &+ P_1 \cdot P_2 \cdot \delta_{12} + P_2 \cdot P_3 \cdot \delta_{23} + P_3 \cdot P_1 \cdot \delta_{31} \end{aligned}$$

but principle of minimum energy

$$\left( \frac{\partial U}{\partial X} = 0, \frac{\partial U}{\partial Y} = 0, \frac{\partial U}{\partial Z} = 0 \right)$$

$$\frac{\partial u}{\partial x} = X \delta_{xx} + Y \delta_{xy} + Z \delta_{xz} + P_1 \delta_{x1} + P_2 \delta_{x2} + P_3 \delta_{x3} = 0$$

$$\frac{\partial u}{\partial y} = X \delta_{yx} + Y \delta_{yy} + Z \delta_{yz} + P_1 \delta_{y1} + P_2 \delta_{y2} + P_3 \delta_{y3} = 0$$

$$\frac{\partial u}{\partial z} = X \delta_{zx} + Y \delta_{zy} + Z \delta_{zz} + P_1 \delta_{z1} + P_2 \delta_{z2} + P_3 \delta_{z3} = 0$$

Oznaczamy:

$$P_1 \delta_{x1} + P_2 \delta_{x2} + P_3 \delta_{x3} = \Delta x_p$$

$$P_1 \delta_{y1} + P_2 \delta_{y2} + P_3 \delta_{y3} = \Delta y_p$$

$$P_1 \delta_{z1} + P_2 \delta_{z2} + P_3 \delta_{z3} = \Delta z_p$$

przenieszczenia.

wyprowadzone

dostatecznie

sił czynnych

$P_1, P_2, P_3$

2 krok:  $\Rightarrow X \delta_{xx} + Y \delta_{xy} + Z \delta_{xz} = \Delta x_R$

displacements caused by hyperstatic forces  $x, y, z$

$$X \delta_{yx} + Y \delta_{yy} + Z \delta_{yz} = \Delta y_R$$

$$X \delta_{zx} + Y \delta_{zy} + Z \delta_{zz} = \Delta z_R$$

displacements caused by active forces  
 $P_1, P_2, P_3$

Ostatecznie

Canonical equations of Force Method for  $x, y, z$

$\Delta x_R$

$$X \delta_{xx} + Y \delta_{xy} + Z \delta_{xz} + \Delta x_p = 0$$

$$X \delta_{yx} + Y \delta_{yy} + Z \delta_{yz} + \Delta y_p = 0$$

$$X \delta_{zx} + Y \delta_{zy} + Z \delta_{zz} + \Delta z_p = 0$$

równanie kanoniczne metody sił

elle razy

bardziej ogólnie  
More generally

Mogą dać:  $X = X_1, Y = X_2, Z = X_3$ , itd

Canonical equations for

$x_1, \dots, x_n$  forces

$$\delta_{11} X_1 + \delta_{12} X_2 + \delta_{13} X_3 + \dots + \delta_{1n} X_n + \Delta 1p = 0$$

$$\delta_{21} X_1 + \delta_{22} X_2 + \delta_{23} X_3 + \dots + \delta_{2n} X_n + \Delta 2p = 0$$

$$\vdots$$

$$\delta_{nn} X_1 + \delta_{n2} X_2 + \delta_{n3} X_3 + \dots + \delta_{nn} X_n + \Delta np = 0$$

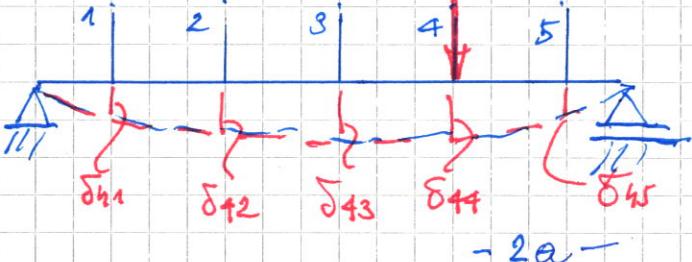
układ równań kanonicznych  
metody sił

Unit displacements

Liczby wpływowe - jako odpowiednie przenieszczenia właściwe statyczne wyznaczające pod oddziaływanie obciążeniem

sił, odpowiadając:  $X=1, Y=1, Z=1$

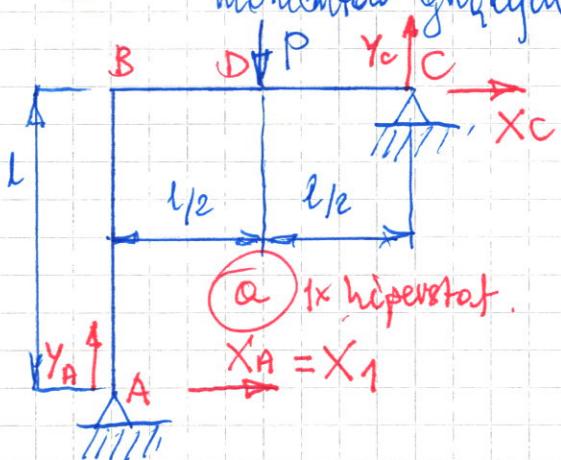
$$P_h = 1$$



$$\delta_{41} = \delta_{14}, \text{ itd.}$$

Ex. 1.

Stosując metodę sił momentów gągających wyznaczyć wykres obciążenia (a)



- rama jednokrotnie hiperstatyczna

(1) warunki statyczne (static eqs.)

$$\textcircled{1} \quad \sum P_i x = X_A + X_C = 0 \quad X_A = -X_C$$

$$\textcircled{2} \quad \sum P_i y = Y_A - P + Y_C = 0$$

$$\textcircled{3} \quad \sum M_i c = Y_A \cdot l - X_A \cdot l - P \cdot \frac{l}{2} = 0$$

4 wektory - 3 warunki statyczne

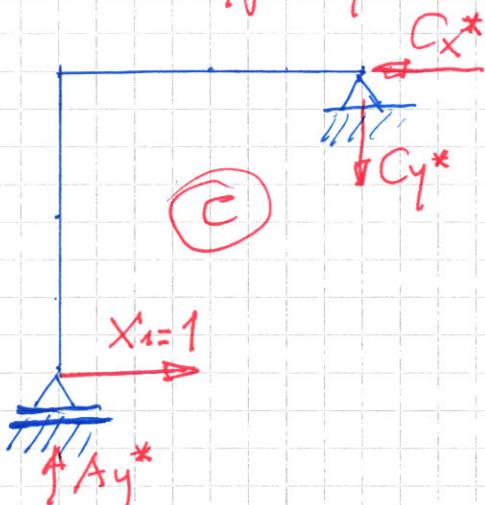
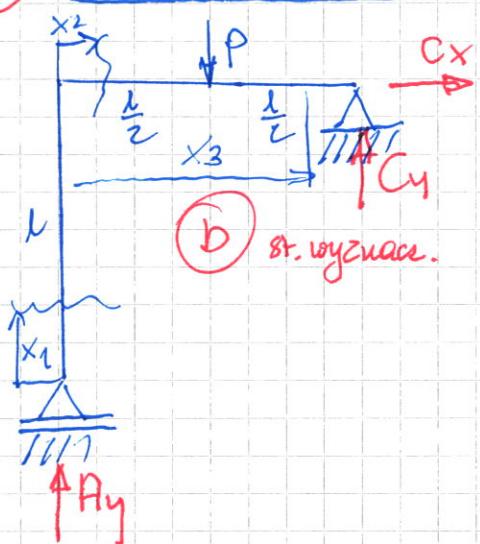
$\Rightarrow$  1x hiperstat.

$X_A = X_1 - \text{wielkość hiperstatyczna}$  (hyperstatic force)

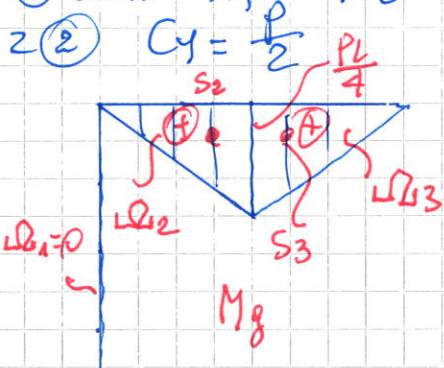
Równanie kinematyczne metody sił. w tym przypadku

$$\textcircled{4} \quad X_1 \delta_{11} + \Delta_{1p} = 0$$

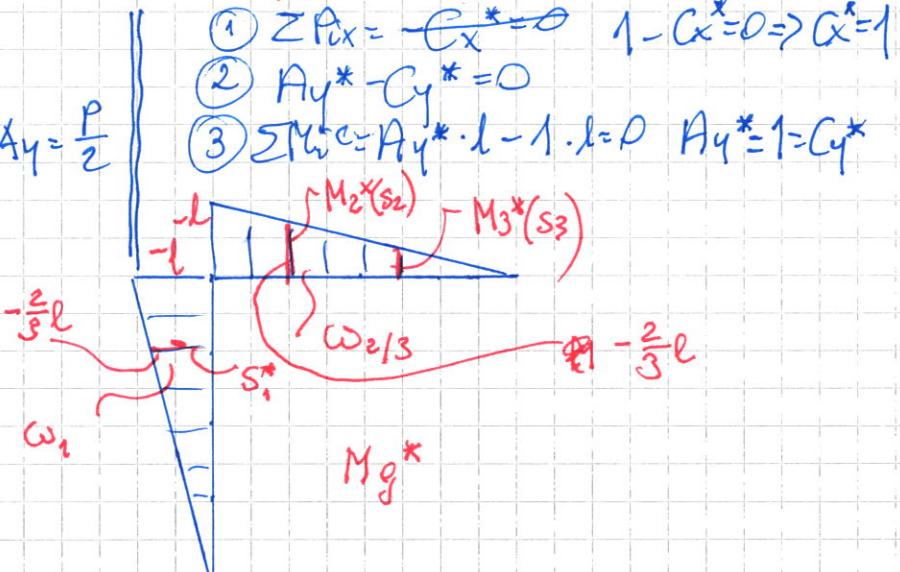
(tylko energ. zginania, bez wychylenia, skruszenia)



$$\begin{aligned} \textcircled{1} \quad \sum P_i x = C_x = P \\ \textcircled{2} \quad \sum P_i y = A_y - P + C_y = 0 \\ \textcircled{3} \quad \sum M_i c = A_y \cdot l - P \cdot \frac{l}{2} = 0 \Rightarrow A_y = \frac{P}{2} \end{aligned}$$



$$\begin{aligned} M_1(x) &= 0 \\ M_2(x) &= A_y \cdot x = \frac{P}{2} \cdot x \\ M_2(0) &= 0 \quad M_2\left(\frac{l}{2}\right) = \frac{P}{2} \cdot \frac{l}{2} = \frac{P l}{4} \end{aligned}$$



$$M_1^*(x) = -1 \cdot x = -x$$

Do wyznaczenia:  $\Delta_{1P}$ ,  $\delta_{11}$  zastosowane metoda MM,  
sposób Werszera

$$\Delta_{1P} \Rightarrow b + c$$

$$\Delta_{1P} = \frac{1}{EI} \left[ \int_0^l M_1(x) \cdot M_1^*(x) dx + \int_0^{\frac{l}{2}} M_2(x) \cdot M_2^*(x) dx + \int_{\frac{l}{2}}^l M_3(x) \cdot M_3^*(x) dx \right]$$

$$= \frac{1}{EI} [Q_1 \cdot M_1^*(s_1) + Q_2 \cdot M_2^*(s_2) + Q_3 \cdot M_3^*(s_3)] =$$

$$Q_1 = P, Q_2 = Q_3 = \frac{1}{2} \cdot \frac{PL}{4} \cdot \frac{1}{2} = \frac{PL}{16}$$

$$M_1^*(s_1) = l, M_2^*(s_2) = -\frac{2}{3}l, M_3^*(s_3) = -\frac{1}{3}l$$

$$\Delta_{1P} = \frac{1}{EI} \left[ 0 + \frac{PL^2}{16} \cdot \left( -\frac{2}{3}l \right) + \frac{PL^2}{16} \cdot \left( -\frac{1}{3}l \right) \right] = -\frac{PL^3}{16EI}$$

$$\delta_{11} \Rightarrow c + c$$

$$\omega_1 = \omega_2 = \omega_3 = \frac{1}{2} \cdot l \cdot (-l) = -\frac{l^2}{2}$$

$$\delta_{11} = \frac{1}{EI} \left[ \omega_1 \cdot Mg_1^*(s_1) + \omega_2 \cdot Mg_2^*(s_2) + \omega_3 \cdot Mg_3^*(s_3) \right] =$$

$$= \frac{1}{EI} \left[ \left( \frac{l^2}{2} \right) \cdot \left( -\frac{2}{3}l \right) + \left( -\frac{l^2}{2} \right) \cdot \left( -\frac{2}{3}l \right) \right] = \frac{2l^3}{3EI}$$

$$(4) \quad X_1 \cdot \frac{2l^3}{3EI} - \frac{PL^3}{16EI} = 0 \quad | \cdot 48EI$$

$$32X_1 - 3P = 0 \Rightarrow X_1 = X_A = \frac{3}{32}P$$

Z warunków statyczki

$$= ① \quad X_A + X_C = 0 \Rightarrow X_C = -X_A = -\frac{3}{32}P$$

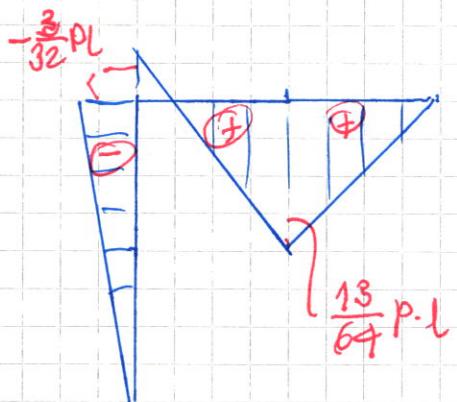
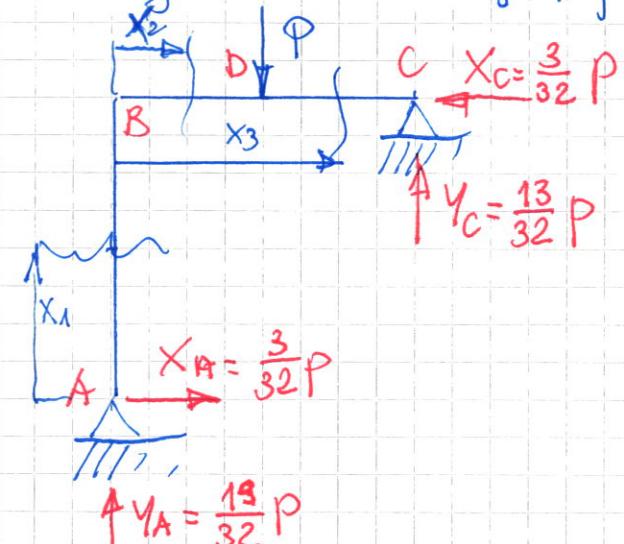
$$= ③ \quad Y_A \cdot l - X_A \cdot l - \frac{PL}{2} = 0$$

$$Y_A \cdot l - \frac{3}{32}P \cdot l - \frac{PL}{2} = 0 \quad Y_A \cdot l = \frac{PL}{2} + \frac{3PL}{32} = \frac{19}{32}P \cdot l$$

$$Y_A = \frac{19}{32}P$$

$$= ② \quad Y_A - P + Y_C = 0 \quad Y_C = P - Y_A = P - \frac{19}{32}P = \frac{13}{32}P$$

Wykres momentów gęzowych



$$0 \leq x_1 \leq l$$

$$M_1(x) = -X_A \cdot x$$

$$M_1(0) = 0, M_1(l) = -\frac{3}{32} P \cdot l$$

$$0 \leq x_2 \leq \frac{l}{2}$$

$$M_2(x) = -\frac{3}{32} \cdot P \cdot l + \frac{19}{32} \cdot P \cdot x$$

$$M_2(0) = -\frac{3}{32} P \cdot l$$

$$M_2\left(\frac{l}{2}\right) = -\frac{3}{32} P \cdot l + \frac{19}{32} P \cdot \frac{l}{2} = -\frac{13}{64} P \cdot l$$

$$\frac{l}{2} \leq x_3 \leq l$$

$$M_3(x) = -\frac{3}{32} P \cdot l + \frac{19}{32} P \cdot x - P \left(x - \frac{l}{2}\right)$$

$$M_3\left(\frac{l}{2}\right) = \frac{13}{64} P \cdot l$$

$$M_3(l) = -\frac{3}{32} P \cdot l + \frac{19}{32} P \cdot l - \frac{P \cdot l}{2} = 0$$